User documentation for switching power supply system S3000-S2A version 4

G¥5

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# 1 INTRODUCTION

This document represents the usage instruction for switching power supply system C3000 C2A version 4 and is designed for device users.

The instruction includes all general data, as well as data related to exploitation, control and maintenance of the system and particular assemblies.

Text of the document is classified in sections containing:

- the first section as an introduction to the document,
- the second section with description of system operation,
- the third section introducing description of system assemblies,
- the fourth section with the most relevant engineering data in relation to the system and system assemblies,
- the fifth section addressing precautionary measures to be taken during the operation in the network field and distribution,
- the sixth section providing the system installation instructions,
- the seventh section providing the instruction manual,
- the eighth section containing testing instructions for the regular checks or those prior to installation,
- the ninth section as a maintenance instruction, i.e. diagnostics' procedure and error recovery,
- supplement section provides electrical diagrams and list of components with codes and supplier information.

Traditionally, GVS team is looking forward to all constructive remarks concerning text contents and its organization, in order to derive future instruction versions more precise, better arranged and highly adaptable to large number of users.

# 2 SYSTEM DESCRIPTION

This section illustrates the switching power supply system C3000 C2A 64, describing its purpose, system characteristics and operation.

# 2.1 Purpose

The switching power supply system  $C3000\ C2A\ 64$  is intended to power supply telephone exchanges and other TT devices, requiring high performances in relation to interference, noise, and response speed. The system is entirely automatic and provides uninterruptable, independent operation, ensuring its usage in maintenance systems, remote facilities with no personnel and DC supply for all consumers.

Switching supply system C3000 C2A 64 outlet provides DC voltage nominal value of 48V and 100A nominal current. System is tested for usage within Russian IITT system. On a special request, the system is designed for other standard values of DC voltage, 24V, 60V and 110V nominal.

Switching supply system C3000 C2A 64 is a modern, highly professional system, provided with exceptional electrical features, easy handling and high reliability.

System allows simple enhancements and modifications, not requiring any interruption of the system operation or harming its basic functions in any way.

The system may operate with or without batteries, diesel aggregates or other auxiliary supply source.

Switching supply system C3000 C2A e4 is stored in the standard cabinet S1.

# 2.2 Operation description

Switching supply system C3000 C2A e4 is designed to operate in rectifier configurations. System includes:

- rectifiers *W1400T48B* 64, maximum 8 rectifiers
- measuring and diagnostics panel  $M \ensuremath{\mathcal{A}\Pi}\xspace$  C36 64 for C2m 64 cabinet
- distribution  $\mathcal{A}200A$  e4 with:
  - two fuse bases for high-performance battery fuses, 250 A nominal current
  - eight fuse bases for high-performance distribution fuses, 125 A nominal current
  - one contactor, 200A nominal current
  - electronic subassembly for undervoltage battery protection  $\Pi 3B2x~e4$
  - two 300A (3mV) shunts for battery and distribution current measuring
  - buses, wire form, isolators etc.

• network field  $MP\Pi 8A10 \ e4$ .

Circuit diagram of the switching supply system C3000 C2A e4 is illustrated in figure 1.

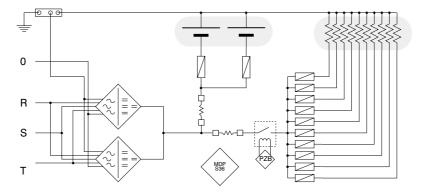


Figure 1: C2A cabinet circuit diagram

#### 2.2.1 System operation description

In regular conditions, input to the system is supplied with three-phase (or one-phase) alternating voltage. Network voltage is rectified and stabilized (using DC-DC converter) to preferred direct output voltage value. Batteries are (re)charged, and their relating voltage (Ub) depends on temperature and battery type.

The system provides energy for consumer supply, with maximum load, and the battery maintenance current. Distribution (consumer) voltage, Ud, is essentially equal to battery voltage, Ub, differing only for a small voltage drop at the system bus.

Total system load is distributed equally to all regular present rectifiers. For a diminutive rectifier load, the system automatically switches off the certain number of rectifiers (*stand-by* mode), thus obtaining the optimal conditions for the remaining ones. Sudden load changes are compensated from the active rectifier resources, and when exceeding their current capacities, battery load is used, temporarily, until a necessary number of (*stand-by*) rectifiers is switched on.

Rectifier currents synchronize with consumption changes, maintaining stabilized output voltage.

Measuring and diagnostics panel  $M\square\Pi$ , via keyboard and display (*LCD* and *LED*), performs system operation control, checks the alarm origin, battery current/voltage capacity and distribution, network voltage and system parameters, enabling parameter entry.

#### 2.2.2 System operation in the event of network supply termination

In situation of total termination of network supply or unstable network voltage (exceeding the allowed range of 176V - 253V), rectifiers are switched off and the entire consumer supply

is battery provided.

Battery voltage drops during the time, thereby consumers supplied in this system configuration must be allowed to operate with a wider input voltage range (40.5V - 57V). On the battery voltage dropped under the allowed value the alarm is generated, and in case of further voltage drop, consumer is eventually switched off.

On network supply recovery, rectifiers are automatically switched on, assuming consumer power supply and battery charging function.

#### 2.2.3 Operation in resource deficiency conditions

It's a complete termination of network supply that most frequently results in failure of network supply or one or two phases. With failure of one or two phases, system maintains the stable output voltage, while the maximum output current goes down to 2/3 or 1/3 nominal output current. Besides the phase failure there may occur a rectifier irregularity. In that case, maximum output current decreases in relation to the number of irregular and regular rectifiers.

Maximum power transmitted to the system by rectifiers in network supply error conditions shall be referred to as Pr. For consumption value less than currently available stream system capacity, system shall function as if in normal operating mode. In the case opposite, system operates with maximum currently available stream capacity, while the rest of energy is battery provided. Such system operating mode is maintained until termination of irregularity condition.

#### 2.2.4 Battery undervoltage

On network supply interruption, battery shall provide consumer supply. Battery voltage decreases continuously, and in case of persisting network supply interruption exceeding the autonomous battery operation, battery voltage shall drop under the allowed level.

Thereby, for battery protection purposes, sound remote alarm on the measuring and diagnostics panel is switched on. If the battery voltage still declines, battery voltage protection shall serve for switching the consumers off the battery and thus preventing the battery discharge and destruction.

On the activation of voltage protection, system goes down, and consumer supply is interrupted until the network supply recovery, when the system automatically continues the operation.

#### 2.2.5 System operation on network supply recovery

On network supply recovery, rectifiers are switched on successively with 60 second delay to obtain network stability, providing energy for battery charging. Loading current is controlled and limited in relation to battery type and capacity. On battery voltage reaching the voltage protection deactivation point, system disconnects consumers automatically. In that moment, rectifiers obtain current sufficient to cover consumer needs, with concurrent battery charging. On battery voltage reaching the maintaining voltage value (depending on temperature and battery type), the battery charging is terminated and rectifiers switch to stand-by mode. Duration of battery charging mode is in the range of few to maximum 14 hours, unless user defined.

In case of EG battery used, battery voltage at the moment of transition to stand-by mode is exceeding the rectifier voltage. Consequently, battery is being discharged for some time until voltage is restored to maintaining voltage value thereby having regular system operation mode reestablished.

When dealing with HI batteries, charging is realized according to control function realized within measuring and diagnostics panel. Charging voltage is equal to maintaining voltage. In the initial phase of charging process, system maintains constant current defined with battery capacity as  $0.3 \cdot C_{10}$ . Based on battery temperature, current limit (Io) and charging voltage Uo are formed for battery current. Once reached charging voltage is being maintained further on. Battery charging voltage controls distribution of rectifier currents, total current and system voltage, on each rectifier level. Thereof, Io current overflow is not allowed, that is, Uo voltage is maintained. Meanwhile, current value is descending, while voltage value remains constant. Duration of HI battery charging controlled in such a matter is not limited. Charging current is a system parameter function and is set to optimum value to prolong battery lifetime.

# **3 ASSEMBLY DESCRIPTION**

This section brings description of measuring and diagnostics panel  $M\Pi C36$  64, distribution  $\Pi 200A$  64, voltage protection  $\Pi 3E2x$  64, network field  $MP\Pi 8A10$  64 and cabinet C2. Description refers to purpose, operating mode, construction etc.

# 3.1 Measuring and diagnostics panel M $\square$ C36 B4

Detail description in user documentation for МДП C36 в4.

#### 3.1.1 Purpose of МДП C36 в4

Measuring and diagnostics panel is a microprocessor controlled device performing: measuring and displaying of corresponding system parameters' values (voltage, current, storage temperature etc.), detection and informing of the system state, controlling battery charging in relation to the temperature of the room the battery block is stored in, communication with other microprocessor controlled system parts, communication with system periphery (*PC*, *modem*, etc), system integration into the independent whole. Single measuring and diagnostics panel controls entire power supply system and is labeled with  $M \square \Pi C36 \ e4$ .

### 3.1.2 Description of МДП C36 в4

Measuring and diagnostics device is contained of  $M \not\square M$  - measuring and diagnostics module, two YMK small universal converter for  $M \not\square M$  logic and communication bus supply, slave mechanical devices, cases for device and connecting parts.

- *MДM* module is a system central module. Its control block is realized over *Intel* microprocessor *80188*, two microcontrollers *HC11* and their slave memory blocks, programmable dual-port memory, *LCD* and *LED* display, user keyboard and alarm elements. *MДΠ* performs following functions: detection and reporting, signaling, measuring and display, system parameter settings, communication functions, protection functions, battery charge control functions and testing functions. All functions shall be discussed in the following sections.
- *YMK* generates dedicated voltages out of a battery voltage:
  - +5 V for MДM power supply;
  - $-\pm 5$  Vb for power supply of measuring and diagnostics blocks on the battery side (distribution power supply)
  - +10 VSC for communication bus supply;
  - +5 Vp for external communication supply and primary/secondary protection.

#### Following are basic M $\Pi$ functions

#### Measuring and display functions relating to:

- battery current and voltage;
- distribution current and voltage;
- network voltage;
- storage temperature (from  $-15,0^{\circ}$ C to  $99,9^{\circ}$ C).

LCD and LED displays used are placed on  $M \slash M$  front panel. Measuring results are expressed with one decimal.

#### Detection and report functions:

- **General alarm** is a logic signal generated on or preceding to failure of a *C3000* system vital part which may be:
  - 1. irregular rectifier;
  - 2. battery voltage below battery undervoltage threshold;
  - 3. distribution voltage exceeding the allowed level (according to IITT standards);
  - 4. battery or distribution fuse blow;
  - 5. detected irregularity of network voltage.

General alarm is sound and remote signalized.

- Sound alarm. On the occurrence of a system error, sound alarm is activated. Sound alarm may be deactivated using the switch on the front panel, in any particular case.
- **Remote alarm**. Remote alarm is generated simultaneously with a sound alarm. Sound alarm deactivation shall never effect the remote alarm functioning nor cause its generation. Remote signaling is realized via relay and appropriate signals,  $A \mathcal{I} M \mathcal{I}^+$  and  $A \mathcal{I} M \mathcal{I}^-$ , connected to serial terminals of cabinet distribution. 24V, 1A relay output contacts are connected in the alarm state.

**Other report functions**. Menu *Status/Alarm status* informs user of different failure events or related system events. See section "Menu options" on *LCD* display. Menus such as: *Battery field, Distribution* or  $\Pi 3B$  inform user of specified values for system/battery voltage and current and possible battery/distribution fuse blow.

### **Protection functions**

- Battery undervoltage protection. Independently from  $\Pi 3B$  module,  $M\square\Pi$  detects battery undervoltage before  $\Pi 3B$  switching off the contactor (for 0.5V earlier) and informs (alarms) user of the possible system operation failure,  $\Pi B$  in menu Alarm status.
- Watchdog timer automatic device protection in irregular operation events. Due to different external effects (electromagnetic interference, power supply related interference), the device may switch to temporary irregular operation state. *MAM* module realizes the function which shall, in maximum 200ms time, provide device being brought back to regular operation. The function is software realized via *Watchdog* timer of microcontroller 68HC11.

### Testing functions

Regularity check for indicator and sound and remote alarm is accomplished in *LCD* display menu, option *Display test*. On selecting this option, all *LED* characters and indicators are activated, as well as sound and remote alarm (if found any).

### Control functions

• Battery (re)charging

Battery charging interval depends on system parameters, consumer capacity, rectifier section power, battery state and storage temperature. The entire process shall take at least several hours.  $M\square\Pi$  controls battery charging on the basis of current optimum values of battery current and voltage, battery storing capacity and temperature. Battery capacity value is in 40 Ah to 9995 Ah range.

### Communication functions

- Communication functions of measuring and diagnostics panel may be classified to those relating to communication with C3000 system (dual, RS485, 4800 Bd) and communication with peripheral devices (RS485, 4800 Bd), to provide continuous or temporary screening and updating of system measuring values. Communication reliability are obtained via: message doubling, communication path doubling, *Hand\_shaking*, time protection, network collision detection.
- Communication with rectifier  $M\square\Pi$  is allowed to inspect all relevant rectifier parameters: regularity, current, temperature, serial number, rectifier status, 220 V network regularity.

### Master control functions

• Current distribution to rectifiers up to 1% of mean system current value for each. With deviation exceeding 25% the rectifier is considered technically irregular.

- System voltage regulation to battery charging/maintaining value.
- Controlling rectifier activation/deactivation to maintain the active rectifier value between 6A and 12,5A.
- Detection of rectifier irregular operation followed with its deactivation.

#### 3.1.3 МДП C36 в4 construction

 $M\!\mathcal{Д}\Pi$  is designed with all functions relevant for a user located on the front panel.  $M\!\mathcal{Д}\Pi$  card is installed on the front upper cabinet side.

 $M \ensuremath{\scale}\xspace\Pi$  front panel view is illustrated in figure 2:

₩5 MDP \$36	123-
aaaa aaaa	
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Figure 2: МДП C36 в4, front view

## 3.2 Distribution Д200А в4

### 3.2.1 Д200А в4 distribution purpose

 $\square 200A \ e4$  distribution is part of C3000 system performing:

- battery connection to the system C3000,
- system C3000 connection to external consumers.

Besides these two basic functions, distribution section also provides battery (re)charging of M1400T48B~64 rectifier.

In the case of network supply interruption, distribution section enables consumer battery supply completely controlled and undervoltage protected.

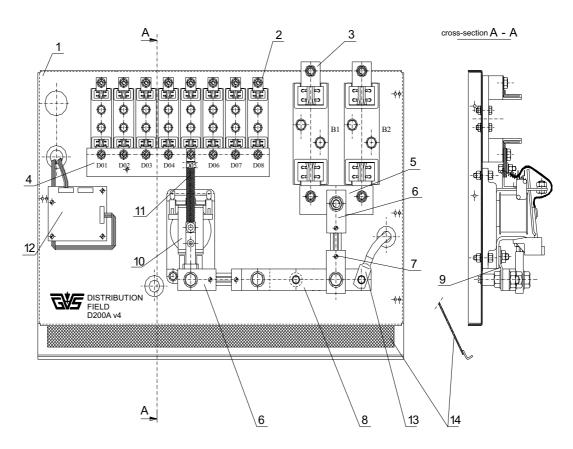
### 3.2.2 Distribution operation description

Distribution contains elements for direct voltage and current distribution.

It is realized as a separate independent whole and is stored at the top of cabinet. One cabinet may have one distribution whole, keeping the distribution modularity facility at the system level; distribution devices from several cabinets in a system may relate as modules, enabling system expansion and flexibility.

Distribution provides two special terminal groups: terminals for batteries and terminals for external consumers. Each of these two groups is provided a necessary number of fuses for planned load/battery. Besides these terminals, distribution structure also includes special circuits for battery discharge protection and shunts for battery charging current measuring.

Distribution  $\angle 200A \ e4$  is installed in configurations without serial convertors. Distribution  $\angle 200A \ e4$  view is presented in figure 3.



Distribution carrier board 2. 125A distribution fuse base;
 250A battery fuse base; 4. Distribution bus; 5. Battery bus;
 Battery shunt; 7. Battery shunt terminals; 8.Rail between shunts;
 Contactor connection to distribution shunt; 10. Contactor; 11. Contactor connection to distribution bus; 12. Undervoltage protection printed board Π3Б2x e4; 13. Cable connecting to B<sup>-</sup> rectifier bus; 14. Protection grid

Figure 3: Distribution A200A 64 view

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#### 3.2.3 Distribution Д200А в4 construction

Distribution  $\mathcal{A}200A~64$  is realized as a compact module with unified protection and signaling elements on its front board.

Distribution is placed at the top of cabinet and fixed firmly to it with screws. Front board is closed with a protection cover, disabling any access to distribution inside.

Distribution may be accessed from the front and upper cabinet side. Unless placed next to the wall, the access from the back side is possible.

 $\Delta 200A$  distribution carrier board is presented in figure 3. Carrier board keeps distribution elements unified in a whole. Following is mounted to the distribution  $\Delta 200A$  carrier board:

- two fuse bases, for 250A nominal current high-performance fuses for battery charging
- eight fuse bases for 125A nominal current fuses for consumer supply
- one contactor, 200A nominal current
- electronic subassembly for battery undervoltage protection  $\Pi 3E2x$  64
- shunt for battery current measuring
- one shunt for consumer current measuring
- buses, wire form, isolators etc.

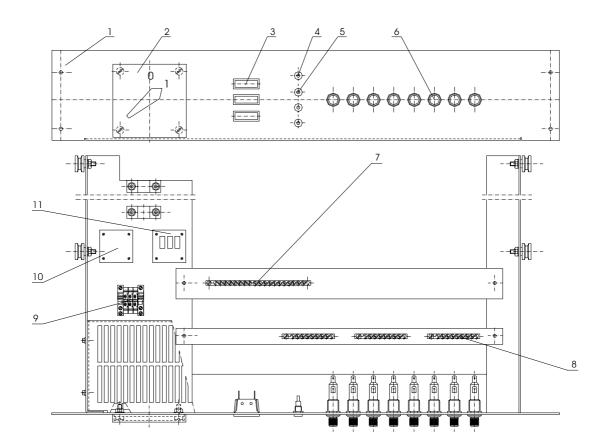
### 3.3 Network field MPП8A10 в4

#### 3.3.1 Purpose

Network field is part of C3000 system and provides the energetic system connection to the mains network supplying the system. It is mounted in C2 and C3 cabinets and delivered thereafter.

All elements required for measuring and signaling of alternative supply presence are contained in the network field.

Network field basic function is to enable C3000 system connection to 230Veff alternative voltage network and its regular functioning. Connection to the network is performed over connection terminals, using supply line.



1. Network field front board; 2. Main switch; 3. Control lamp; 4. Measuring receptacles; 5. Fuses; 6. Zero bus; 7. Phase buses; 8. Phase serial terminal; 9. Printed board; 10. MMH; 11. Printed board PCO

Figure 4: MPII8A10 64 network field view

Eight fast meltable fuses is mounted onto network field front board, providing input overload and short-circuit protection for M1400T48B~64 rectifier, thereby preventing negative network effects to system operation, possible in network irregularity conditions.

Network field defines input voltage values so as to control supply quality and detect supply irregularities. Measuring is performed using four measuring receptacles on the front network field board, in 1:1 ratio, using appropriate measuring instrument.

During network field operation, three lamps on the front board perform continuous indication of phase input voltage presence.

Figure 4 presents MPII8A10 64 network field view.

#### 3.3.2 Network field operation description

 $MP\Pi 8A10~64$  network field is delivered with complete internal wiring, ready for connection to network supply. On supply lines connected, network field may operate.

Switching the main switch on (position 2) network field and its belonging rectifiers are energized. Lamps are illuminated (position 3), signalizing network voltage presence for each phase separately.

Input voltage for each rectifier is provided over inlet fuses.

After power-up, network field functions regularly to the moment of possible network irregularity occurred, which shall be discussed in section 8.

Network field deactivation is performed using main switch.

#### 3.3.3 Network field construction

Network field *MRP8A10* is realized as compact unique module with command, protection and signaling elements unified on its front board and connection elements to network and rectifiers on the carrier board. Network field also includes *MMH* board for phase voltage measuring.

Network field elements are accessed from the front side and, when necessary, from the back side. Network field opening is simple and quite obvious.

After unscrewing the front board screws (see figure 4 position 6), network field may be removed from cabinet construction (wheel transfer), with end stop provided. Removing the end stop, network field can be entirely extracted from the system.

The upper network field section is installed a protection grid, providing protection from accidental energized part contact and extraneous element interference that might result in damages.

#### 3.4 Cabinet C2 в4

#### 3.4.1 C2 B4 cabinet purpose

C2~64 cabinet is designed to store the uninterruptable power supply system, with power up to 11KW. Maximum eight rectifiers M1400T48B~64, distribution  $\mathcal{A}200A~64$ , network field  $MP\Pi8A10~64$  and measuring and diagnostics panel are mounted in the cabinet.

#### 3.4.2 C2 B4 cabinet description

C2~64 cabinet is so-called "half-height" cabinet. It is intended to place on the floor, possibly with back side next to the wall.

C2 64 is designed for small and medium systems (capable of maximum 200A current delivery). Distribution  $\mathcal{A}200A$  is stored in the upper cabinet section.

Two racks are mounted under distribution section, storing eight modules (rectifiers or serial converters). Cabinet is accessed from the front and upper side. Cabinet dimensions are shown in figure 5.

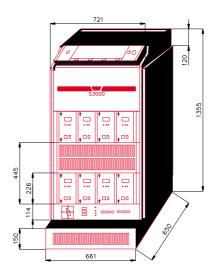
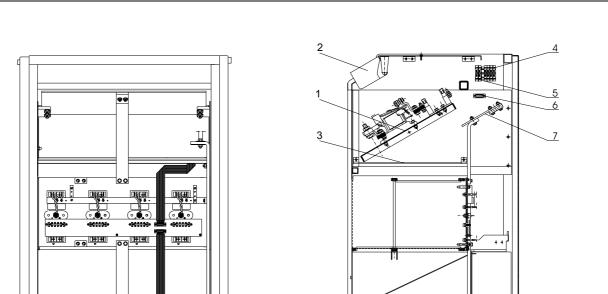


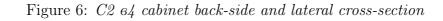
Figure 5: C2 64 cabinet

C2A e4 cabinet back side and cross-section view are presented in figure 6.



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 Distribution Д200А e4; 2.МДП C36 e4; 3. Protection grid; 4. Serial terminals for temperature probe; 5. Serial terminals for remote signalling;
 Connector for external communication; 7. Bus B+; 8. Earthing bus



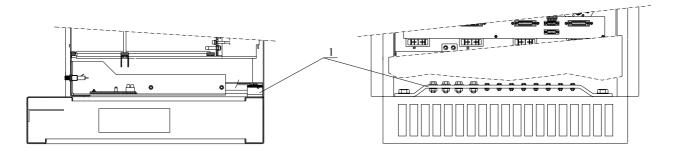


Figure 7: Earthing bus position on C2A cabinet and lateral cross-section

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#### 3.5 ПЗБ2х в4 undervoltage protection board

#### 3.5.1 ПЗБ2х в4 purpose

 $\Pi 3B2x$  module is intended for battery protection from exceeded discharge. This protection is realized by interrupting the line connecting consumer to the battery, using appropriate contactor.  $\Pi 3B2x$  is battery supplied and continuously monitors battery voltage. On battery voltage reaching the upper threshold,  $\Pi 3B2x$  activates the contactor.

#### 3.5.2 ПЗБ2х в4 description

 $\Pi 352x$  undervoltage protection board is realized in the analog technology. Comparator devices detect battery undervoltage, generating the alarm signal. Comparator thresholds are set during manufacturing process by means of trimmer potentiometers with value depending on battery type and number of cells in battery field. Contactor is controlled over switching transistor with maximum 1A output current.  $\Pi 352x$  may independently control operation of two contactors. The board is connected to system over three connectors. Operation principle is illustrated in figure 8.

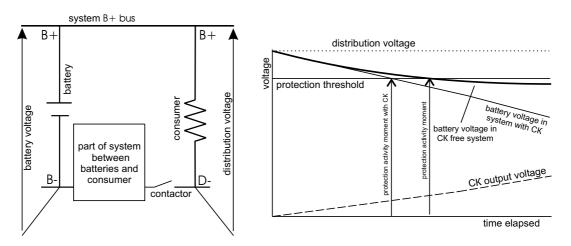


Figure 8: Block diagram and graphic with description of II3E2x purpose

Figure proves the contactor interrupts the battery-consumer circuit, disconnecting consumer from the battery and preventing its further discharge. Graphic shows system voltage time diagrams. Protection threshold represents the voltage value resulting in protection activity (consumer disconnected). On protection activated, not only consumer, but all other unnecessary system elements causing battery discharge are disconnected from batteries.

On battery voltage drop below the threshold adjustable by board trimmers, comparator switches off the corresponding FET. On FET being switched off, circuit through contactor coil and distribution lines are interrupted.

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The other comparator half is used for battery undervoltage signaling, activated some time before consumer disconnection. The board also contains contactor switch on signaling part. Contactor microswitches are serially connected to realize "AND" function. With deactivation of a switch, the circuit is interrupted thus signalizing protection activity. If there was an undetected contactor in the system, corresponding microswitch is switched over by means of corresponding DIP switch activation.

The board is fully equipped with signaling types selected by user. Further text introduces the list of output pins with description of relative functions.

K1-, K2-: This pins control contactor coil. Contactor is activated in the event of low pin voltage (FET activated). 100V FETs are used (for 110V systems another FET shall be introduced). Contactor coil circuit for standard versions  $\Pi 3E9305~64$  should not exceed 1A.

VK1+: With VK1+ on mass, all system contactors are switched on. This is regular state (if not so, system exercises certain difficulties).

ΠHC: Bringing this signal to mass, battery undervoltage is signalized some time before protection activity. Modern exchanges may use consumer discrimination (deactivation of less important consumers) in the event of battery energy reaching minimum to signalize the system operation interruption approaching on predefined time expiry.

The board provides selection of two thresholds for undervoltage protection activation introducing the external *I*IK signal, over J1 connector. Bringing this signal to mass, undervoltage protection threshold is getting lower for 0.16 V per cell in relation to set threshold value. This enables the variable undervoltage protection activation threshold in processor controlled systems within range of 1.65 V per cell - 1.81 V per cell. In case of sudden battery discharge, (detected with processor measuring of battery current and time) bringing *I*K signal to mass may modify undervoltage protection activation threshold (to 1.65 V per cell). In such circumstances, processor may deactivate the contactor in any moment while the voltage value is between 1.65 V per cell and 1.81V per cell, simply by getting the signal back to higher voltage value. This is how variable threshold of the undervoltage protection activation is achieved within *C3000 e4* system, selected from *MAM* keyboard.

#### 3.5.3 ПЗБ2х в4 board construction

 $\Pi 3B2x$  module is a printed board with dimensions 91.44 x 76.20 x 1.6 mm. This board is fixed onto specified distribution location using four M<sub>3</sub> screws to the board corners. Disposition of components on  $\Pi 3B2x$  board is illustrated in figure 12.

### 3.6 Network voltage measuring board MMH B4

#### 3.6.1 MMH B4 board purpose

*MMH* network voltage measuring module provides detection of network voltage state for all three phases. During measuring process, network and control electronics are galvanic isolated.

Effective voltage value is measured for all three phases and results are forwarded to  $M\square\Pi$  where the measured values are displayed by means of LCD. Measuring accuracy is 1%.

## 3.6.2 MMH B4 board construction

MMH module is a printed board, dimensions 91.44 x 76.20 x 1.6 mm. The board is fixed onto specified location in the network field using four M<sub>3</sub> screws to the board corners.

# 4 ENGINEERING DATA

# 4.1 Engineering data for C2A B4 system

# Input data:

220/230 Veff
47-63 Hz
-15% to $+10\%$
30%
8 x 7A
$< (8 \ge 8A)$
$> 0,\!98$
10A
overvoltage,
undervoltage, fuse,
lightning surge
protection

### Output data for 48V output voltage system:

Nominal voltage Vi	48V
Adjustable maintaining voltage	49-59V
Adjustable charging voltage	52-56V
Stability	better than $1\%$
Nominal current	8 x 25A
Current restriction	8 x 26A
Output power	$8 \ge 1400 W$
Response duration	1ms
Voltage surge amplitude	less than 2Vp-p
Psophometer value of battery-free noise voltage	less than 1mVeff
Effective noise value within range 10Hz - 450kHz	less than $25 \text{mV}$
Broadband noise	less than $10 \mathrm{mVeff}/\mathrm{MHz}$
Rectifier dedicated protection	overvoltage, undervoltage,
	overcurrent,
	short-circuit protection

#### General data:

Processor control	RS 485 interface
Module operating frequency	50kHz
Allowed ambient temperature	$0^{\circ}C$ to $+$ $40^{\circ}C$
Allowed storage temperature	$-10^{\circ}\mathrm{C} \mathrm{~to} + 70^{\circ}\mathrm{C}$
Allowed humidity	up to $90\%$
Distribution fuses	high-performance meltable
Battery fuses	high-performance meltable
Temperature protection	$69^{\circ}\mathrm{C}$
Battery undervoltage protection	adjustable
Automatic battery (re)charging	
Indicating instruments	digital $1\%$
Alarms	Sound, remote
Modular assembly	
External dimensions:	
height	1357mm
width	$661 \mathrm{mm}$
depth	620mm
mass	115kg
Mean time between two failures	40 years
Spare part provision	20 years
Warranty	3 years
<b>A 1 1 1 1 1 1 1 1 1 1</b>	
Certification	ЗЈПТТ

## 4.2 Engineering data for МДП C36 в4

### 4.2.1 МДМ СЗ6 в4

Consumption: maximum consumption on +5V is equal to 500mA,  $\pm 5V_b$  at the source: 40mA, on  $+5V_p$ : 20mA. Maximum consumption on 48V is equal to 250mA. **Communication** External: RS485, 4800 Bd, both way Internal: RS485, 4800 Bd, dual communication channel with maximum consumption of 2A. **Battery (re)charging** 

- HI batteries: current limit is specified depending on temperature and charging voltage i.e. maintaining voltage
- EG batteries: charging started with 200 mA/Ah in relation to total battery capacity; charging stopped with 20 mA/Ah in relation to total battery capacity.

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• USER batteries: user defines thresholds and specified voltages and charging currents.

Maximum number of monitored distribution fuses: 8. Maximum number of monitored battery fuses: 2. Remote signaling: dead relay contacts, maximum 24V, 1A, connected in the alarm state. Display refresh rate: 8kHz. Sound signaling: buzzer, 5V direct voltage, 80dB.

#### 4.2.2 Engineering data for VMK0102

- Input voltage: 35 75V
- Input current: 120mA 600mA
- Output voltages:  $\pm 10V, \pm 5V, \pm 5V_b, \pm 5V_p$
- Output current: up to 3A for +10V, up to 1A for +5V, 150mA for other voltages
- Operating frequency: 50kHz.

## 4.3 Engineering data for Д200А в4

 $\square 200A$  64 distribution output data for 48V output voltage:

Nominal voltage (Vi)	48VDC
Nominal current	200A
Output fuses	
distribution	$8 \ge 125 \text{A}$ - meltable
battery	$2 \ge 250 \text{A}$ - meltable
Protection	fuses, battery undervoltage protection, contactor
Measuring	battery shunt 300A, 3mV
	distribution shunt 300A, 30mV

#### General data:

Allowed ambient temperature	$0^{\circ}C$ to $+$ $45^{\circ}C$
Allowed storage temperature	$-10^{\circ}$ C to $+75^{\circ}$ C
Allowed humidity	up to $90\%$
Spare part provision	20 years
Warranty	3 years
Certification	ЗЈПТТ

## 4.4 Engineering data for MPΠ8A10 в4:

### МРП8А10 в4: network field input data

Network voltage Vu	220/230 VAC
Network frequency	47-63 Hz
Allowed voltage phase deviation	-15% to $+10\%$
Input current on full load	
and nominal input voltage	3 x 20A
Main switch	$3 \ge 40A$ , (three-pole)

### $\rm MP\Pi8A10~B4$ network field output data:

Nominal voltage Vi	220/230 VAC			
Output meltable fuses	10A			
Protection	fuse			

#### General data:

Allowed ambient temperature	$0^{\circ}$ C to $+$ $45^{\circ}$ C
Allowed storage temperature	$-10^{\circ}$ C to $+75^{\circ}$ C
Allowed humidity	maximum $90\%$
Spare part provision	20 years
Warranty	3 years
Certification	ЗЈПТТ

## 4.5 Engineering data for Π3Б2x в4

- Input voltage: 48V nominal
- Allowed deviation: 24 80V
- Input current: 25mA
- Maximum current for contactor coil: 1A (on request, up to 10A)

- Output fuses: 3A each
- $\bullet$  Dual threshold selection of undervoltage protection activation: 1.8 or 1.65 V/cell
- Adjustable protection threshold:
  - 42V 46V for 48V systems (threshold 1.8 V per cell)
  - -51V 56V for 60V systems (threshold 1.8 V per cell)
  - 38V 42V for 48V systems (threshold 1.65 V per cell)
  - 46V 51V for 60V systems (threshold 1.65 V per cell)
- Two protection activity thresholds
- Signalizing the prospective protection activation

# 5 PRECAUTIONS

Besides common precautions considered in operation with electrical equipment, specified by corresponding legal regulations, and those related to elements installed in system C3000-C2A, network field  $MP\Pi 8A10$  and distribution  $\mathcal{A}200A$ , described in corresponding instructions, following issues should be applied:

- no installation work, testing, repair and similar activities by an unauthorized and untrained person are allowed;
- device in the active state conducts dangerous voltages and accumulated energy;
- device enclosure and other metallic parts of network field are connected to protection earthing via appropriate supply line conductor;
- when conducting certain activities at the network field, the network automatic fuses and related switch in the distribution cabinet providing C3000 system supply should be switched off;
- when operating with distribution (fuse replacement, shunt measuring etc., with tool usage) consider avoiding short circuit on the energized elements;
- buses, contactor, shunts, are not isolated, being stored internally in the distribution, thereby requiring strong attention when using appropriate tools and equipment during distribution interventions;
- during fuse replacement consider avoiding its reaching the electronic boards;
- all system and module interventions are forbidden for the warranty duration period (except the fuse replacement); each intervening activity results in complete warranty dismission and user being charged for servicing.

# 6 INSTALLATION

This section illustrates installation procedure for C2 system and assemblies, demountable by user. Corresponding conditions required for system installation are also introduced. Network field, racks and distribution are delivered in connection with the cabinet and its installation is performed in GVS.

GVS provides complete system installation, unless required different by purchaser. In case of purchaser taking over the system installation, GVS is obliged to deliver the tested and appropriately set system.

## 6.1 System installation conditions

To enable C3000 system installation, following conditions should be completed:

### • System storage conditions

C3000 system is intended for storage within rectifier, exchange, operating or other environment. It requires no special air conditions. System storage area should be illuminated and dry, according to corresponding regulations.

### • Network supply

Network supply switchboard should be placed near the system, with a main switch and a number of fuses according to system configuration. Number of fuses is defined within power supply design project, providing three fuses for each rectifier cabinet. Cross-section of supply line from the main switchboard to the network supply switchboard is defined for each system separately, within power supply design project.

### • Battery supply

System battery supply requires supply lines for each battery. Cable cross-section depends on its length and current provided from the battery. Battery cables are specified according to calculation results. GVS conducts battery cables to the corresponding connecting points (fuses, terminal spots or batteries) in maximum 5m length, unless other specified by the contract.

### • Battery forming

Batteries may be formed in accordance with relating manufacturer instructions or investor regulations. GVS company shall not consider battery forming as part of C3000 system installation.

However, GVS may perform battery forming, when specified by contract, and according to procedure described in corresponding GVS instructions.

### 6.2 МДП C36 - C2 mounting

Measuring and diagnostics panel should be installed into C2 system. Mounting procedure is simplified and includes only  $M\square\Pi$  mounting to the cabinet and connecting relating distribution connectors to the device. Wire form should be connected with  $M\square\Pi$  C36 - C2 over two 64-pole connectors, J1 and J2, taking care of connector labels. J1 and J2 connectors are divided into 4 segments (J1-1 to J1-4 and J2-1 to J2-4) connected to specified points.

### 6.3 Network supply connection

Network field is delivered connected to the cabinet. Entire installation is performed in GVS company. Network field installation outside the factory implies only connection of appropriate supply lines out of system (network supply).

Network line connection is performed in non-energized state, fixing the screws to serial terminals. After connecting to the network field, supply line is fixed to network field construction with two tipples.

To execute the installation procedure:

- make sure that the main output switch for connection to network field is in switched off ("0") position; output terminal is located in user distribution cabinet;
- make sure the main network field switch is in position "0"
- unscrew four front board screws
- extract the network field from the cabinet, to the position allowed by end stop
- unscrew supply line clamps
- insert supply line phase conductor endings into connection terminal (figure 4 position 9) and fix the screw
- insert supply line zero conductor ending into "zero" bus (figure 4, position 7) and fix the screw;
- insert supply line protection conductor ending into "earthing" bus (figure 7, position 1) and fix the screw;
- fix supply lines using clamps
- push the network field slowly into the shelf and fix it with screws on the network field front board
- connect supply line to cabinet terminal providing power supply.

With all previous performed, the installation is complete.

On the installation complete, network field operation is started switching on the main front board switch (see section 7).

**Note**: Recommended supply line is five-wired PPOO-Y cross-section type in accordance with system installation conditions (main cabinet distance etc).

### 6.4 Direct supply and consumer switch on

Distribution part is delivered firmly connected to the cabinet so the field installation requires only cable connecting.

Installation in the field is performed as following:

- unscrew distribution protection mask screws (the cover with ΓBC label on it) and remove it. Access to distribution inside is enabled.
- connect battery cables (- pole) to battery fuses (figure 3, position 3) and fix them using a screw.
- connect battery cables (+ pole) to B+ cabinet rail.
- connect consumer cables (- pole) to distribution fuses (figure 3, position 2) and fix them with a screw.
- connect distribution cables (+ pole) to B+ cabinet rail
- place meltable fuse insertions into bearings using isolation handle;
- apply protection mask and fix it to the cabinet.

Distribution part is ready for operation.

**Note:** Perform cable connecting in de-energized state, either by disconnecting the main cabinet switch or removing the insertion of related fuse. When removing the fuse insertion without switching off the main switch, consider the energized elements and strictly observe precautions supplied in section 4.

### 6.5 Rectifier installation and connecting

Rectifiers are installed as following:

- make sure that the rectifier activation switch is in position "0" (downwards);
- place *U1400T48B* e4 rectifier into rack slides and pull it along to the utmost position (notice the moment connectors reach the back panel);

• turn the rectifier on and set the rectifier activation switch to position "1" (upwards).

Module positioning within C2 cabinet

If not requiring the full configuration installed, thus leaving the empty space in the rack, it is recommended to position it in the middle of the rack. In the case of two empty positions required, make it the second and fourth from the left.

# 7 INSTRUCTION MANUAL

This section introduces handling procedure for C2A system and related assemblies, as concerning users. In addition, system reactions in particular situations are described.

# 7.1 C2A B4 system handling

C2A system is totally automatic, monitoring own operation and reporting (using visual, sound and remote alarm) noticed system errors. During system operation,  $M\square\Pi$  makes certain system parameters available for user, on user request. User is also enabled to define system operation selecting system parameters.

### 7.1.1 System handling in regular operation

In regular operation, the system supplies consumers while batteries remain in stand-by mode. Network supply is detected. All system rectifiers are regular, some being in the active state, and others remaining in stand-by mode, depending on system load. Consumer voltage depends on battery type and ambient (battery) temperature. Values are presented in the following table.

Battery type	Mode	Temperature	Number of cells	Battery voltage	
				range	
HI	maintaining	$0^{\circ}\text{C}$ - $35^{\circ}\text{C}$	24	56.4V	53V
EG	charging	$0^{\circ}\text{C}$ - $35^{\circ}\text{C}$	24	58.8V	55.2V
EG	maintaining	$0^{\circ}\text{C}$ - $35^{\circ}\text{C}$	24	56.4V	52V
USER	charging	$0^{\circ}C - 35^{\circ}C$	24	49.2V	55.2V
USER	maintaining	$0^{\circ}C - 35^{\circ}C$	24	52.8V	57.6V

Total system current (towards battery and consumers) is equally distributed along active rectifiers, with difference between rectifier currents not exceeding  $\pm 0.2$ A.

In case of system load decreased, certain active rectifiers switch off for ten minute period, while others distribute current according to previously described procedure.

In case of increased system load, certain stand-by rectifiers switch off (for ten minute period) and distribute current according to previously described procedure.

On system detecting decreased battery capacity or considerable (20% of capacity) battery maintaining current during the operation, system switches to battery charging mode. Battery charging shall last until the batteries are fully charged, but not longer than time (in hours) specified in user menu.

In regular operation,  $M\square\Pi$  provides user the access to different system parameters (battery and distribution current and voltage, temperature, network voltage, battery field parameters etc.) and description of alarms detected in system.

Various alarms detected within system are described in details over LCD (see description for  $M\square\Pi$ ). System reports the alarms visually (light emitting diodes and LCD), using sounds ( $M\square\Pi$  buzzer) and by remote closing the relay contacts connected into the system according to user needs. Sound alarm may be deactivated only during the elimination of whatever caused it.

On the alarm reported, user starts the elimination procedure and the system continues its regular operation.

### 7.1.2 Manual settings of system parameters

Depending on assigned priority, user may define following system parameters: display light, display accuracy correction of temperature and current voltage values; specification of battery capacity, number of battery cells, upper and lower threshold for switching to battery charging mode, allowed battery charging time, minimum battery voltage and voltage control mode, battery type, maintaining and charging voltage for user battery type, current limit for battery charging. User may save these parameters or restore the default ones.

User may introduce the system into forced battery charging mode with corresponding conditions provided, or restore it to stand-by mode, select one of the available languages (English, Serbian, Russian) and set the system time and date.

- Display light is specified from  $M \square \Pi$  menu, selecting the value for LED display, within range 1-15.
- Display accuracy correction. User may perform display zero correction for all five measured values to provide display accuracy. All corrections are conducted from MДΠ menu. Unprofessional usage of this option, that is, incorrect voltage/current measuring may endanger regular system operation.
- Battery capacity may be specified within range of 45Ah 9995Ah. For total battery field, it is required to gather capacities of all batteries parallel connected. Notice that the current limit and battery charging mode thresholds depend on selected capacity.
- Number of battery cells is specified solely in case of system being required to operate with smaller or bigger voltage value, e.g. 60V. Therewith, it is necessary to provide corresponding rectifiers for the expected distribution voltage.
- Setting the lower and upper battery charging mode threshold. Lower threshold may be set to a value within range 1-199Ah, and the upper to value 10-1999Ah. In case of changed battery capacity, thresholds are set automatically to 1/5 of battery capacity.
- Allowed time for battery charging. This is time defined by user for batteries to remain in charging mode, unless conditions were provided for charging mode termination in relation to current criteria. Minimum is 10 minutes while the maximum specified time is 100 hours.

Minimum battery voltage. User primary selection may be defined relating to voltage specifying mode in ΠΗБ control menu, selecting permanent (fixed), manual or automatic option. Fixed minimum battery voltage is defined with number of cells and is product of number of battery cells multiplied by 1.80. Note that *MДΠ* is blocked only by *Π3Б* reacting on 1.83V per cell so the main battery protection for *MДΠ* in error conditions is realized by *Π3Б* board. Manual selection of minimum battery voltage may vary in range of 15V-110V, thus enabling operation within different systems. User should calculate voltage per cell value. Automatic setting for minimum battery voltage is realized with *MДΠ* monitoring the speed of battery discharge and defining minimum voltage according to following table. For more than 20 hours of charging, minimum battery voltage is defined with 1.80V per cell.

up to	1h	2h	3h	4h	5h	6h	7h	8h	9h	10h
1.6	5	1.66	1.67	1.68	1.68	1.69	1.70	1.71	1.71	1.72
111	n	12h	13h	14h	15h	16h	17h	18h	19h	20h
1.7	3	1.74	1.75	1.75	1.76	1.77	1.77	1.78	1.79	1.79

Table 1: Minimum discharge voltage per cell dependance with discharge time function

- User selects one of battery types: HI, EG or USER (user defined type). More detailed description of battery types is supplied in battery charging section.
- Maintaining and charging battery voltage are defined solely for USER batteries and may be specified in range 2.20-2.40V per cell for maintaining voltage and 2.05-2.30V per cell for battery charging voltage. Notice that these voltages are defined for 20°C temperature conditions and when specified by user, their values depend on 20°C temperature value.
- Current limit is also specified solely for USER batteries, in range 0.05-0.50 of battery capacity.

## 7.1.3 Battery charging

 $M\!\!\mathcal{Д}\Pi$  controls battery charging on basis of present optimum battery current and voltage values, relating capacity and room temperature.

# HI leak-proof battery type charging

With network voltage during normal operation, batteries are supplied with small current. On error detected within system (e.g. network voltage loss), battery current drops suddenly and changes direction, after which system is battery supplied (discharging current varies in proportion to consumption). In case such state lasts longer, exceeding default battery autonomous duration, undervoltage shall occur.

On network voltage recovery, current "overwhelms" the battery.  $M \square \Pi$  enters battery charging mode, maintaining the current limit  $Io = 0.3C_{10}$ .  $C_{10}$  battery capacity provides ten hour autonomous operation.  $M \square \Pi$  commands rectifier charging mode acting as current source, Iocurrents, all until battery voltage reaches Uo charging voltage value defined with voltage per cell in function with working temperature.

°C	0	1	2	3	4	5	6	7	8	9	10	11
V/c	2.350	2.345	2.340	2.335	2.330	2.325	2.320	2.315	2.310	2.305	2.300	2,297
°C	12	13	14	15	16	17	18	19	20	21	22	23
V/c	2.294	2.291	2.288	2.285	2.282	2.279	2.276	2.273	2.270	2.266	2.262	2.258
$^{\circ}\mathrm{C}$	24	25	26	27	28	29	30	31	32	33	34	35
V/c	2.254	2.250	2.246	2.242	2.238	2.234	2.230	2.226	2.222	2.218	2.214	2.210

Table 2: Charging voltage/cell dependance with working temperature function (HI batteries)

On battery voltage reaching *Uo* value (charging voltage), current value starts descending and shall retain the value corresponding to stand-by mode. Maintaining voltage of HI batteries is equal to charging voltage.

Figure 9 illustrates HI battery charging process. Top graphic shows battery voltage and the bottom one specifies battery current.

- $t_1 = time of network voltage loss;$
- $t_2 = time of network voltage recovery;$

 $t_3 = time of maximum rectifier power.$ 

System operates regularly until  $t_1$  moment in time.

- t<sub>1</sub> t<sub>2</sub>: system is battery supplied; battery current varies in proportion to consumption; battery voltage persistently drops, possibly leading to battery undervoltage occurrence. In this case, system operation is paused until network voltage recovery.
- t<sub>2</sub> t<sub>3</sub>: network voltage is restored, rectifiers switch on and current loads the battery. *Io* current limit is reached and  $M \not\square \Pi$  keeps this current value constant while rectifiers serve as current sources all until battery voltage reaches *Uo* value defined with number of cells and battery storage temperature.
- t<sub>3</sub>: batteries are still being charged, with voltage approaching constant value equal to *Uo* and descending current value. For leak-proof HI type batteries, this voltage presents maintaining voltage as well, thereby battery current in further operation conforms to charging/maintaining voltage.

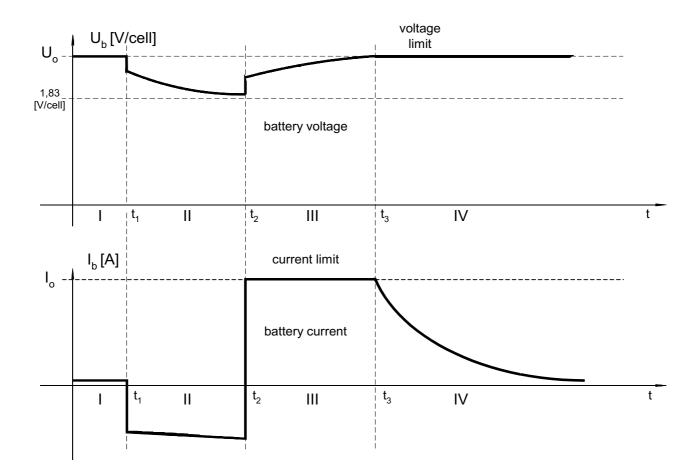


Figure 9: HI battery charging

#### EG battery type charging

EG battery type charging is different than HI battery charging. EG battery charging voltage is not equal to maintaining voltage and consequently, system behaves accordingly.

Current limit in charging mode is derived from equation  $Io = 0.3C_{10}$ . Rectifiers act as current sources, *Io*currents, until battery voltage reaches *Uo* charging voltage value defined with voltage per cell in function with working temperature. Charging voltage per cell dependence with temperature is illustrated in table 3.

°C	0	1	2	3	4	5	6	7	8	9	10	11
V/c	2.450	2.445	2.440	2.435	2.430	2.425	2.420	2.415	2.410	2.405	2.400	2,395
°C	12	13	14	15	16	17	18	19	20	21	22	23
V/c	2.390	2.385	2.380	2.375	2.370	2.365	2.360	2.355	2.350	2.347	2.344	2.341
$^{\circ}\mathrm{C}$	24	25	26	27	28	29	30	31	32	33	34	35
V/c	2.338	2.335	2.332	2.329	2.326	2.323	2.320	2.316	2.312	2.308	2,304	2,300

Table 3: Charging voltage/cell dependance with battery temperature function (EG batteries)

On battery voltage reaching Uo charging voltage value, current value drops and on reaching lower threshold, 20 mA/Ah of full capacity,  $M\square\Pi$  commands stand-by mode. Uc, maintaining voltage, also depends on battery storage temperature. Maintaining voltage per cell dependance with temperature is illustrated in table 4

°C	0	1	2	3	4	5	6	7	8	9	10	11
V/c	2.350	2.343	2.336	2.329	2.322	2.315	2.308	2.301	2.294	2.287	2.280	2,275
°C	12	13	14	15	16	17	18	19	20	21	22	23
V/c	2.270	2.265	2.260	2.255	2.250	2.245	2.240	2.235	2.230	2.227	2.224	2.221
$^{\circ}\mathrm{C}$	24	25	26	27	28	29	30	31	32	33	34	35
V/c	2.218	2.215	2.212	2.209	2.206	2.203	2.200	2.194	2.188	2.182	2.176	2.170

Table 4: Uc/cell dependance with temperature function (EG batteries)

Charging threshold values primarily depend on battery capacity and their values are expressed in relative mA/Ah amounts.

Figure 10 presents charging process for EG type batteries.

- $t_1 = \text{time of network voltage loss;}$
- $t_2 = \text{time of network voltage recovery};$
- $t_3 = \text{time of rectifier maximum power;}$

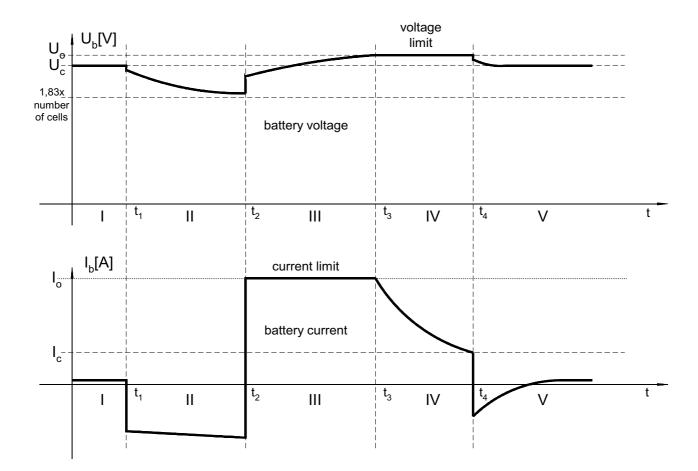


Figure 10: EG battery charging

System functions regularly until  $t_1$  moment in time.

- $t_1 t_2$ : system is battery supplied; battery current varies in proportion to consumption; battery voltage value is descending;
- $t_2 t_3$ : network supply is recovered, rectifier switches on and current loads the battery; *Io* current limit is reached and  $M \square \Pi$  keeps this current value constant while rectifiers serve as current sources all until battery voltage reaches *Uo* value;
- $t_3 t_4$ : batteries are still being charged with voltage approaching constant value equal to Uo and descending current value; for leak-proof EG type batteries, current threshold Ic is also defined, below which batteries switch to maintenance mode with maintaining voltage Uc.

#### User defined battery charging

USER battery charging differs from HI or EG battery charging in the way that certain variables are defined by user, such as: charging voltage, maintaining voltage and current limit. Charging is realized similar to EG battery charging only with different parameters specified, temperature dependant. When selecting parameters correspondent to EG batteries, system acts as if containing EG batteries. Also, when selecting parameters correspondent to HI batteries, system considers HI batteries used. Batteries are presented with corresponding graphics.

#### 7.1.4 System handling on network power dump

In case of one or two phase failure (for three-phase network connection), regular phase rectifiers activate and assume load as described above. Network alarm is generated.

In case of network power dump, rectifiers cease the operation and consumers are battery supplied (if possessing any). On network supply recovery, **all** system rectifiers are switched on successively reaching battery voltage and assuming consumer supply, while system enters battery charging mode. 15 minutes later system shall complete current distribution along rectifiers and start deactivation of unloaded rectifiers.

In case battery discharged during network power dump and the undervoltage protection activated (set to 43,2V), all power supply subsystems shall turn off. On network supply recovery (with battery voltage above 41V), rectifiers switch on successively and battery loading is started. Undervoltage protection is activated and consumers are disconnected. Depending on number of rectifiers and battery capacity, this state remains until battery voltage reaches 48V and undervoltage protection deactivates. Consumers are connected to power supply while  $M \square \Pi$  is activated, starting system re-initiation procedure of around 3 minute duration. In this period  $M \square \Pi$  shall receive no requests from user interface. 20 minutes later, system enters the steady state, with current distribution, while battery (and distribution) voltage value persistently increases, with speed corresponding to the battery charging speed.

If battery voltage drops under 40 V during network power dump and no self-starting rectifier is provided, system shall not be able to restart so the batteries should be charged to 41V voltage.

#### 7.1.5 Handling in the alarm event

On system irregularity occurred or detection of a vital system part, the system shall generate the alarm automatically.

User is informed by means of visual, sound or remote alarm (see 3.1.2, M $\square$  C36 description, Detect and inform functions). Alarm cause is presented on LCD and seven segment display. Following table shows the alarm indications.

			A	LARM DISI	PLAY
	LCD	LED	BUZZER	REM. ALARM	
ПБ	- undervoltage protection	+	+	+	+
НД	- distribution voltage,	+	+	+	+
	out of range				
НИ	- irregular rectifier	+	+	+	+
AM	- network alarm	+	+	+	+
БО	- battery fuse	+	+	+	+
ДО	- distribution fuse	+	+	+	+
TEM	- high temperature	+	+	-	-
ИСЗВ	- deactivated sound alarm	+	+	-	-
УК	- contactor activated	+	-	-	-
PP	- operation mode	+	_	-	_

On the alarm information received user starts repairing of whatever caused the alarm and performs activities according to specified alarm conditions. Meanwhile, sound alarm may be deactivated but after completion of previous activities, it is **necessary** deactivated.

Alarm generating conditions and its recovery are presented in the following table:

ПБ	Undervoltage protection or minimum battery voltage: alarm reported for
	battery voltage under allowed value $(1.83V/cell)$ possibly implying con-
	sumer switching from the battery (on $1.80$ V/cell, battery may be dam-
	aged). Most frequently, these condition is caused by power dump. De-
	pending on activities defined in the internal object instructions, user ac-
	tivates stand-by supply set or allows system "crash" until network supply
	recovery. If assumed that the alarm appeared for system irregular opera-
	tion condition, $M\square\Pi$ and $YMK$ should be reset and relating authorized
	service informed.
НД	Distribution voltage out of range: alarm is reported for distribution volt-
	age out of range 50V - 57V, according to Serbia and Montenegro $\Pi TT$
	regulations.
НИ	Irregular rectifier: alarm is reported on a rectifier failure and indicated
	with rectifier light emitting diode and current value. User should replace
	the irregular rectifier. This signal may also appear in bad network voltage
	conditions (under 187V or over 253V on a phase), having some or all
	rectifiers failed.
AM	Network alarm: reported in case of one or several phase failure (indication,
	network field lamps) or network automatic fuse failure. If there's a miss-
	ing phase check for error in distribution cabinet (supplying system with
	network supply); otherwise, wait for network supply recovery. In case of
	network fuse blow, check rectifier regularity prior to fuse replacement.
БО	Battery fuse: use $LCD$ and voltage measuring to detect the burned fuse
	and replace it.
ДО	Distribution fuse: use $LCD$ and test measuring to detect the burned fuse
	and replace it.
TEM	High temperature: alarm reported for battery ambient temperature out
	of range 0°C - 35°C. User should obtain ambient working temperature
	switching the air-condition device on. If temperature probe is disconnected
	or temporary deactivated, alarm is generated and display shows 20°C. If
	temperature probe is short circuited, alarm is generated and display shows
	19.9°C. User should check and replace the probe, probe cable and terminal.
ИСЗВ	Sound alarm deactivated: alarm is reported on user switching off the sound
	alarm switch.
УК	Contactor switched on: informing of the undervoltage protection not ac-
	tivated.
PP	Operation mode: informing of the system being in battery charging
	(stand-by) mode.
<u></u>	

If any indicator (*LCD*, *LED*) on  $M \square \Pi C36$  are not operative, reset  $M \square \Pi$  and YMK.

#### **Rectifier indication**

Each rectifier front side contains three seven segment displays for rectifier current preview and one light emitting diode for rectifier state indication. Display shows following:

actifier quitched off intentionally or regulting from network gupply				
ectifier switched off, intentionally or resulting from network supply				
ımp.				
MK rectifier communication electronics is irregularly supplied.				
User should replace the rectifier, reset YMK, check the connect				
wire form with the back panel at the rack back side.				
ectifier operating, rectifier output current presented.				
ectifier within current limits. Detect system overload cause and				
ure it.				
easuring error on display. Replace the rectifier.				
nitting diode indication:				
NDICATION				
egular operation. Rectifier on A bus under $M \square \Pi$ control.				
ectifier deactivated, for overheating.				
ectifier intentionally switched off, small system load.				
etwork alarm. Rectifier activated 60s after network recovery.				
ectifier started (after reset), not controlled by $M \square \Pi$ .				
o communication between rectifier and $M \square \Pi$ , either along A bus				
B bus.				
ectifier on B bus.				

With combination of the above rectifier indications, user defines its regularity.

# 7.1.6 Handling in МДП C36 failure conditions

On occurrence of system operation error caused by partial or entire  $M \square \Pi C36$  irregularity, perform VMK reset, pulling out and restoring VMK supply connectors. After reset,  $M \square \Pi$ starts system initiation with 3 minute maximum duration. If  $M \square \Pi$  still remains irregular, the authorized service should perform replacement of  $M \square \Pi$  and VMK. During this replacement, system is not turned off, it operates without  $M \square \Pi$  control, with continuous output voltage and current distribution to rectifiers, depending on their relating characteristics.

# 7.2 Measuring and diagnostics panel МДП C36 в4 handling

# 7.2.1 Front panel commands

Front panel contains following parts (figure 11):

- sound alarm switch on/off switch: "0" switch position indicates deactivated sound alarm that won't react in case of system error;
- device display with *LCD* and *LED* sections; *LCD* displays data relating to each system part, while *LED* displays only user most relevant values;
- keyboard for controlling *LED* and *LCD* display and corresponding  $M \square \Pi$  functions.

#### 7.2.2 Keyboard

 $4 \ge 4$  keyboard with ten digits (0-9) and four menu navigating keys is used. Keyboard with keys' description is illustrated in figure:

1	2	3	◀-	<ul> <li>Back to previous menu or previous input clearing</li> </ul>	
4	5	6	<b>↑</b>	<ul> <li>Navigating the menu upwards</li> <li>Navigating the menu downwards</li> </ul>	
7	8	9	₩	<ul> <li>Entering the input</li> <li>Back to previous menu</li> </ul>	
*	0	•	<b>↓</b> ]	Decimal point	

All keyboard functions relate to LCD display and output contents. To provide required output on LED display one should select an option in  $M\square\Pi$  menu, LED output submenu on LCD. The input of corresponding parameters mainly refers to  $M\square\Pi$  menu and current time and date. Other input contents are factory set, with only informing user of set system parameters or values. Since LCD displaying is done using drop-down menus, arrow keys are used to navigate these segments and switch from one to another menu option.

# 7.2.3 Display

Front side of measuring and diagnostics panel contains two displays, one LCD display with 2 x 16 characters and one seven-segment LED display with 2 x 4 characters.

LED display is divided into two sections with four D1 and D2 digits each. D1 display is used for description of D2 output value or, if displaying current on D2, D1 is used for voltage value output. Front panel also contains six LED indicators signalizing following failure events, in order left to the right:

- irregular rectifier;
- battery voltage below limit or distribution voltage out of range;
- battery or distribution fuse failure;
- network alarm, phase failure or phase voltage out of range;
- temperature out of range or temperature probe disconnected;
- sound alarm deactivated.

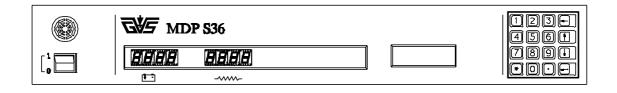


Figure 11: MAII C36 64, front view

# 7.2.4 LCD display menu options

LCD display menu options are presented in following table:

1. RECTIFIER	2. SERIAL	3. DISTRIBUTION
	CONVERTOR	
1.1 Present	2.1 Present	3.1 Distribution
rectifiers	current	
1.2 Active	2.2 Active	3.2 Distribution
rectifiers	serial convertors	voltage
		3.3 Fuse condition
		3.4 Shunt current
		3.5 Shunt voltage
4. BATTERY	5. МДП	6. STATIC
FIELD		SWITCH
4.1 Battery current	5.1 LED output	6.1 Network Ueff
4.2 Battery voltage	5.2 Display light	6.2 inverter Ueff
4.3 Temperature	5.3 HC11 pair condition	6.3 Consumer Ieff
4.4 Number of cells	5.4 Coupler type	6.4 Power factor
4.5 Battery capacity	5.5 Shunt voltage	6.5 U network frequency
4.6 Battery type	5.6 Shunt current	6. 6 U inverter frequency
4.7 Specified voltage	5.7 Serial convertors	6. 7 Duty
4.8 Specified battery current	5.8 Ub zero correction	6.8 T network testing
4.9 Loading time	5.9 Ub angle correction	6.9 T inverter testing
4.10 Allowed	5.10 Ud zero correction	6.10 Ueff network gauge
loading time		
4.11 Low current threshold	5.11 Ud angle correction	6.11 Ueff inverter gauge
4.12 High current threshold	5.12 Ib zero correction	6.12 Network gauge
	5.13 Ib angle correction	6.13 U inverter gauge
	5.14 Id zero correction	
	5.15 Id zero correction	
	5.16 Temperature zero	
	correction	
	5.17 Temperature angle	
	correction	
	5.18 Battery capacity	
	5.19 Number of cells	
	5.20 Low current threshold	
	5.21 High current threshold	

	5.22 Allowed loading time	
	5.23 Minimum battery	
	voltage	
	5.24 Battery type	
	5.25 Maintaining voltage	
	5.26 Charging voltage	
	5.27 Current limit	
	5.28 User priority	
	5.29 ПНБ control	
7. SYSTEM	8. NETWORK FIELD	9. STATUS
7. SYSTEM 7.1 Language	8. NETWORK FIELD8.1 I phase voltage	9. STATUS     9.1 Display test
7.1 Language	8.1 I phase voltage	9.1 Display test
7.1 Language7.2 Time	8.1 I phase voltage 8.2 II phase voltage	9.1 Display test 9.2 Current time
7.1 Language7.2 Time	8.1 I phase voltage 8.2 II phase voltage	9.1 Display test9.2 Current time9.3 Control variable
7.1 Language7.2 Time	8.1 I phase voltage 8.2 II phase voltage	9.1 Display test9.2 Current time9.3 Control variable9.4 Alarm status
7.1 Language7.2 Time	8.1 I phase voltage 8.2 II phase voltage	9.1 Display test9.2 Current time9.3 Control variable9.4 Alarm status9.5 Static switch
7.1 Language7.2 Time	8.1 I phase voltage 8.2 II phase voltage	9.1 Display test9.2 Current time9.3 Control variable9.4 Alarm status9.5 Static switch9.6 Forced loading

 Table 5: LCD display menu options

**Note**: Since no serial converters are currently used in C2A 64 system, this menu option is reserved for future system versions. "Static switch" option is not used in C2A system either; however, same measuring and diagnostics panel is used in the inverter cabinet so this option is found in the menu, with detail description in the inverter cabinet documentation.

	LED OUTPUT         LANGUAGE         CONTROL								
LEI	OUTPUT	LANGUAGE		L					
			V	/ARIABL	E				
Ub Ib	Battery	SERBIAN - LATIN	Uo	Io	Upp				
Ud Id	Distribution	ENGLISH	68.1	60	1				
Ub	Battery voltage	RUSSIAN							
Ib	Battery current								
Ud	Distribution								
	voltage								
Id	Distribution								
	current								
°C	Battery temper-								
	ature								
Uo	Specified voltage								
Io	Specified current								

Submenus are presented in the following table:

	ALARM STATUS				TIME	1	DATE
УК	TE	ИЗ	НИ	AM	I: Time		I: Date
БО	ДО	ПБ	HC	PP	21.59.30		21.03.1999
	DISTRIBUTION			ПНБ CONTF	ROL	BATTERY TYPE	
		FUS	ES				
	Dist	ributi	on fus	ses	$\Pi HE \text{ control}$		
00000000000000000000				00000	fixed (manual	, auto-	HI (EG, USER)
					matic)		

Table 6: Submenu display options

- One of nine value may be selected for *LED OUTPUT*. Left of the table contains output type and the calling value's on the right.
- Submenu *LANGUAGE* enables user selection of one of three languages offered. On request, additional language matrix may be delivered.
- CONTROL VARIABLE provides monitoring of system module controlling. Uo value is for current specified voltage, Io value for current limit, and UPP is a control variable sent as correction while controlling the system. Its preferable value should be 0.
- STATUS indicates failure type or the state or function currently realized in system. Abbreviations on display correspond to certain events: УК- contactor activated, TE- temperature out of range or temperature probe disconnected, ИЗ- sound alarm deactivated, НИ- irregular rectifier, AM- network alarm, BO- battery fuse blow, ДО- distribution

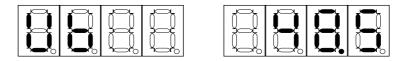
fuse blow,  $\Pi B$ - battery undervoltage, HC- irregular serial converter, PP- duty function set (only for EG or USER batteries).

- *TIME* is set entering data for hours 0...23, minutes 0..59 and seconds 0...59. These values are separated with decimal point.
- DATE is set entering the day 01...31, month 01...12 and year 1000...9999. On  $M\square\Pi$  activation, this value needs to be subsequently entered.
- $\bullet$  DISTRIBUTION FUSES indicates fuse blow. Sequence number corresponds to fuse position in distribution.
- *ΠHB CONTROL* used for selection of control type (fixed, manual, automatic).
- BATTERY TYPE used for selection of battery type (HI, EG or USER).

#### 7.2.5 LED display

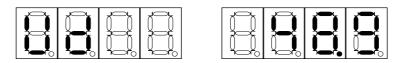
LED display provides representing of battery voltage and current values, distribution voltage and current values, and individually, battery voltage Ub, distribution voltage Ud, battery current Ib or distribution current Id value. In addition, current battery temperature °C, specified charging voltage Uo or specified current limit during battery charging Io may be displayed. To obtain a certain output on LED display, one should select corresponding option in  $M\square\Pi$  menu, LED output submenu on LCD.

A1.Battery voltage display



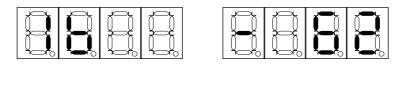
Battery voltage (*Ub*) may value: 48V: 40.5 - 57.0 according to IITT standards (35.0 - 75.0 displayed)

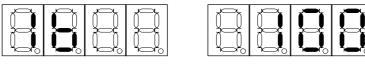
#### A2.Distribution voltage display



Distribution voltage (Ud) may value: 48V: 40.5 - 57.0 following IITT standards (35.0 - 75.0 displayed)

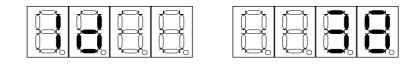
#### A3.Battery current display





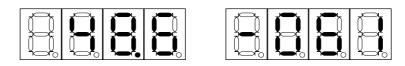
Battery current (Ib) may value: -300A to +300A for C2 system

#### A4.Distribution current display

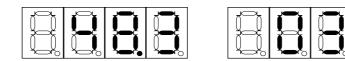


Distribution current (Id) may value: 0A to +300A for C2 system

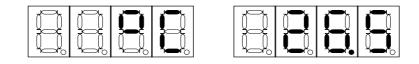
A5. Battery current and voltage display



#### A6. Distribution current and voltage display

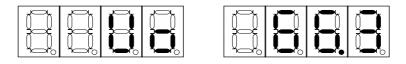


#### A7. Battery (ambient) temperature



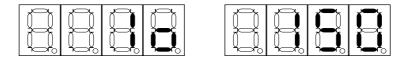
 $\begin{array}{c} {\rm Battery\ temperature\ (^{\circ}{\rm C})\ may\ value:}\\ -15.0^{\circ}{\rm C}\ -99.9^{\circ}{\rm C},\ {\rm with\ disconnected\ probe\ value\ presented\ is\ 20.0^{\circ}{\rm C}}\\ {\it LED\ temperature\ indicator\ is\ illuminated} \end{array}$ 

#### A8. Specified battery charging voltage



Battery charging voltage Uo values: 53.1V - 56.4V for HI battery type 52.1V - 58.8V for EG battery type

#### A9. Specified current restriction during battery charging



Current restriction values: 12A, for 40Ah batteries, up to 1800A for 6000Ah batteries

#### 7.2.6 МДП C36 в4 settings

All settings are factory performed, in accordance with system characteristics. *GVS* provides factory parameter setting for each system separately, on purchaser request. Provided no special requests were defined by purchaser, parameters are set to standard use values.

# 7.3 Handling procedure for Д200A в4 distribution and MPП8A10 в4 network field

Network field and distribution device handling includes only switch on and off. Procedures in case of failure shall be also described. These procedures may be performed by personnel trained to operate with energetic equipment based only on the instruction contents. Still, consider the instruction first, before calling the maintenance service, which is to further obey the section 9.

#### 7.3.1 Switch on/off

No centralized switch on/off is reserved for  $\Delta 200A~64$  distribution device. With C3000 system in operation, distribution is energized consequently.

Single switch on/off is enabled for distribution fuses. To switch the consumer off the C3000 system, use fuse remove handle to remove the fuse link. Switch on is performed in reverse order.

#### 7.3.2 Network supply presence control

One control lamp (figure 4, position 3) is dedicated for each phase, to signalize network voltage presence.

On network supply switched on (position 1), control lamps are illuminated, indicating the activity of the phase.

On network supply switched off (position 0), control lamps are not illuminated.

#### 7.3.3 Input network voltage measuring

Input network voltage measuring for all three phases is realized on MMH module and forwarded to  $M\Pi$ , or manually performed with measuring receptacles.

Besides the control lamps on network field front board, there are four measuring receptacles on the right side (figure 4, positions 4 and 5). Upper receptacle is connected to neutral conductor, and the other three ones to phase conductors  $L_3$ ,  $L_2$ ,  $L_1$  (respectively).

To perform phase voltage measuring connect the measuring instrument into first receptacle and one of the remaining three, depending on the phase voltage measured.

To perform inter-phase voltage measuring, connect measuring instrument into receptacles 2-3, 2-4 or 3-4, depending on the inter-phase voltage measured.

#### 7.3.4 Direct voltage/current measuring

Battery and distribution direct voltage/current is easily measured.

To conduct battery current measuring, apply the endings of measuring device onto battery shunt endings (figure 3, position 7). Make sure that the battery is connected to system and the battery fuse link is in its carrier part.

To conduct consumer voltage/current measuring, apply the endings of measuring device onto distribution shunt endings (figure 3, position 10). Make sure the consumer is connected to the system.

#### 7.3.5 Reactions in case of network supply failure

Network field  $MP\Pi 8A10~64$  is a device with provided long and reliable operation, requiring no interventions.

If network field is not operating (control lamps are not illuminated), check network automatic fuses. If fuses are switched on, check the regularity of relating fuses in the main distribution cabinet supplying the network field. If everything's set correct and system's still not operating well, call maintenance service.

#### 7.3.6 Reactions in case of direct supply failure

 $\Delta 200$  distribution device provides long, reliable operation, with no interventions required.

When BO indicator on measuring and diagnostics panel is illuminated, replace battery fuse link. Replacement procedure is described in section 8.

When  $\square O$  indicator on measuring and diagnostic panel is illuminated, replace distribution fuse link or activate the automatic fuse that made a reaction.

On irregularity signaling persisting after fuse replacement, call maintenance service.

#### 7.4 Undervoltage protection instruction manual

#### 7.4.1 Handling

Handling includes  $\Pi 3B2x$  card switch turning on and off. Disposition of switches and microswitches on the board is illustrated in figure 12.

SW1 switch enables undervoltage protection circuitry start up. Turning the switch off causes a forced reaction of undervoltage protection, that is, distribution contactor is switched off disconnecting consumer D-line.

Microswitch (U7) provides simulation of another nonexistent contactor (VK2+, VK2-) signaling. For example, for K2 missing contactor, switch "2" is switched to position "ON"; for K1 missing contactor, switch "1" is switched on. Signaling of one or another contactor may be switched, since it might be useful to connect the contactor to J3, and not to J2.

J1 connector is used for connection to  $M\square\Pi$ . J2 and J3 connectors are used for connection to contactors. C2A cabinet has only one contactor, connected to one of those two connectors. Microswitch is set to appropriate position. Microswitches "3" and "4" are used for factory setting of undervoltage protection activation threshold and no other position is recommended.

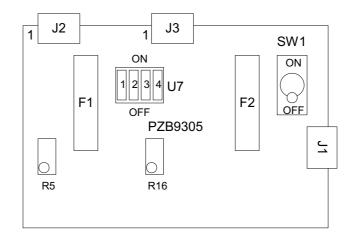


Figure 12: Component disposition on  $\Pi 3E2x$  64 board

On F1 or F2 fuse blow, replace it with the regular one. Trimmer potentiometers R5 and R16 adjust the undervoltage protection threshold setting and are factory set.

#### 7.4.2 Settings

 $\Pi 3E2x$  board provides setting facilities for protection activity threshold.

Protection threshold is the input voltage value for contactor disconnection. This value depends on the number of battery cells and amounts to 1.8V per cell. Protection threshold voltage for 24 cells is equal to  $43.8 \pm 0.1$ V.

According to battery manufacturer specifications, and considering discharge speed, another threshold values may be set.

Threshold is set using trimmers R5 and R16 on  $\Pi 3B$  board within 0.1% tolerances of threshold voltage presented in the table (this is around 50 mV deviation).

Setting is done switching the potentiometer according to following:

 $U_b$  battery voltage is measured. Threshold voltage is designated with  $U_p$ . Comparator input voltage should amount to:

$$U = (Ub/Up) \cdot 2,5V \tag{1}$$

Following issue is voltage measuring in the comparator input point and setting the measured value switching the potentiometer. If battery voltage or another supply voltage (in case the board is not battery supplied) changed meanwhile, calculated value shall not be valid and the setting shall be irregular.

This kind of setting is nondestructive and may be applied in particular, previously installed supply system, with no interruption of its operation. However, due to ever present non-linearity of used components, this kind of setting, although quite satisfactory, is not the most precise one. The alternative setting may be the one realized using a testing board (see 8.7).

In this case, setting is realized by modifying the input voltage  $U_b$  simulating the battery voltage, with provided variable supply source. On  $U_b$  voltage reaching the value of protection threshold for the first or second contactor, *LED* diodes illuminate,  $D_1$  or  $D_2$ , respectively. Consequently, settings follow the algorithm below:

- a) Set  $U_b$  to a large value.  $D_1$  and  $D_2$  are turned off. Further setting relates to first contactor threshold. Same procedure is applied for the second one.
- b) Decrease  $U_b$  voltage value until *LED* diode  $D_1$  is illuminated.
- c) If *LED* illuminates at required threshold voltage value, setting is complete. Otherwise, turn potentiometer in corresponding direction to change the threshold value accordingly.
- d) Increase battery voltage until  $D_1$  is turned off.
- e) Proceed with item b), to the end of procedure.

This setting principle is much better than the first one, since preciseness depends only on preciseness of instrument performing measuring, plus, for the first case, non-linearity caused error included. GVS recommends the second described setting principle, with appropriate conditions provided.

Each potentiometer has independently adjusted related contactor threshold. This enables the facility of earlier or later (priority) disconnection of power supply for different consumers, with appropriate installations provided.

Also, both contactors may be set to simultaneous disconnection, with parallel fat commands.

# 8 TESTING INSTRUCTION

# 8.1 System testing instruction

Switching supply system C2A provides factory, acceptance and user system testing. On user level, system monitoring and basic function tests are provided. More detailed tests on acceptance level (requiring consumer disconnection) should be performed in cooperation with manufacturer and only with certain system features being under suspicion.

During user system testing, system should complete following basic functions:

- 1. Rectifiers are started on public distribution network and rectifier activation.
- 2. Distribution voltage is stable in load change conditions and corresponds to suggested voltage.
- 3. System load is equally distributed along rectifier modules.
- 4.  $M \not\!\!\! \mathcal{A} \Pi$  receives commands, performs measuring and displays system parameters and alarms.

# 8.2 Functionality testing procedure

Switch the network supply on using cam switch on tested system.

Set  $M\square\Pi$  to distribution voltage/current measuring mode. Switch all rectifiers on and specify nominal load. Wait until system distributes rectifier current values evenly.

- 1. Modify load in steps, from current to Inom. Distribution voltage measured on  $M\square\Pi$  is not changed for more than  $\pm 0.6$ V in relation to nominal voltage (real load voltage) and corresponds to specified voltage values.
- 2. Switch the network voltage off for couple of minutes, in case system is connected to battery field. Consumer is battery supplied,  $M\square\Pi$  measures distribution voltage and current. On network voltage activation (after couple of seconds) all rectifiers are started and  $M\square\Pi$  measures battery charging current. Verify start up switching all rectifiers off, and than switching them on, one by one or pulling them out and back, one by one. Tests should be done for real load.
- 3. For real load, (wait for 10 min), rectifier currents should equalize to  $\pm 0.4$ A.
- 4. Make sure that  $M\square\Pi$  receives commands via keyboard, measures and displays battery and distribution voltage/current and that the alarm is reported on switching the rectifier and public distribution network (cam switch) off.

System completed requirements after all above tests passed.

#### 8.3 МДП C36 в4 testing instruction

Do not open  $M\!\!\mathcal{Д}\!\Pi$  during its testing.

#### 8.3.1 Testing equipment installation

Depending on tested function following should be provided:

- To check distribution current, connect voltmeter (mV) to distribution shunt. Depending on shunt and  $M \not\square \Pi$  settings, measured millivolt shunt value corresponds to distribution current in amperes (100 mV shunt), that is, 10 A per millivolt (30 and 60 mV shunt).
- To check battery current, connect voltmeter (mV) to battery shunt. Depending on shunt and  $M \not\square \Pi$  settings, measured millivolt shunt value corresponds to battery current in amperes (30 mV shunt), that is, 10 A/mV.
- To check communication between  $M\square\Pi$  and rectifiers, connect minimum two rectifiers. Rectifier currents equalized after some time indicate regular communication between  $M\square\Pi$  and rectifier.
- To check battery temperature, connect temperature probe to serial cabinet terminals. After 3-5 minutes, use thermometer to measure battery temperature value in the spot close to temperature probe.
- All other checks are realized via keyboard and display.

#### 8.3.2 Testing procedure

For prior-to-testing preparations, reset  $M\square\Pi$  using switch at the back side. Wait for 3-5 minutes until all modules are initiated. Meanwhile, LED displays 00.0 value for Ub voltage.

Provided  $M\square\Pi$  device is regular, following shall occur during the activation: *LED* displays battery voltage values while *LCD* displays "menu, rectifier". Compare distribution and battery current values with values measured in cabinet measuring points. These value should correspond to each other with 1% of deviation. Compare distribution and battery voltage values with values measured in cabinet measuring points. Allowed deviation is also 1%. Allowed deviation for thermometer measured value is 1 to 2 °C.

To confirm distribution fuse blow, measure the voltage value on fuse endings. In case of a fuse blow, voltage amounts from 20 to 70V and  $M \square \Pi$  registers of it using *LED* indicators, that is, *LCD* display. In case opposite, voltage value is expressed in millivolts. **Do not perform ohm check for fuse blow, voltage check solely**.

In case of battery fuse blow, no failure is detected until fuse voltage reaches 0.7 - 0.9V. Measuring the voltage on fuse endings, it is checked whether  $M\square\Pi$  has properly registered this failure.

To test remote alarm operation, perform an indirect check, provoke any system failure (e.g., switching the rectifier off, HH signal - irregular rectifier - is generated). Use the instrument to detect possible short circuit on remote alarm output terminals (cabinet serial terminals).

In all cases of  $M\square\Pi$  registering something that never really happened inside system, such as considerable measuring error or detection of nonexisting system element failure, or undetected existing system failure, follow the instructions for the case of failure.

#### Note:

Disposition of connector pins and serial terminals is illustrated in the supplement. Certain pins are reserved for certain purposes and should not be used for any other than that, for it might cause  $M \square \Pi$  operation irregularities.

# 8.4 Testing instructions for Д200А в4 distribution

Distribution functional tests are performed at the assembly functionally connected to other configuration assemblies.

#### 8.4.1 Testing in de-energized state

- visually check connection of elements, junctions and links;
- use ohmmeter on switched off device to check characteristic conductive connections linking subassemblies into a functional whole; meltable insertions of battery and distribution fuses should be extracted from its bearings:
  - $D^-$  to mass no connection
  - $B^-$  to mass no connection
  - $B^-$  to common shunt point no connection
  - $B^-$  to mass short circuit
  - shunts to  $D^-$  no connection, close contactor contacts short circuit.

#### 8.4.2 Testing in duty mode

Functionality test for  $\Delta 200$  distribution assembly is reduced to  $\Pi 3E2x$  subassembly operation test in real operating conditions. Battery undervoltage protection testing shall be described in section 8.6.

Fuse voltage drop should not exceed 200mV.

# 8.5 Testing instruction for MPII8A10 B4 network field

Network field functionality tests are realized at the assembly functionally connected to other configuration assemblies.

#### 8.5.1 Testing in de-energized state

- switch off the man distribution cabinet switch, setting the handle into position "0";
- check connection of elements, junctions and links;
- use ohmmeter to check characteristic conductive connections linking subassemblies into a functional whole:
- apply black test lead to the first contact of the first network automatic fuse (phase  $L_1$ ). Apply red test lead to the first and than fourth terminal (from left to the right) on the first serial terminal JP1; proper junction shall be confirmed by appropriate tone;
- apply black test lead to the second contact of main front board switch (phase  $L_2$ ). Apply red test lead to second, fifth and eighth terminal of serial terminal JP1;
- apply black test lead to the third contact of main front board switch (phase  $L_3$ ). Apply red test lead to third and sixth terminal of serial terminal JP1.

#### 8.5.2 Testing in energized state

• set the main switch on, with handle in position "1".

Perform voltage measuring applying the black test lead into upper receptacle (figure 4, position 4) and red test lead into one of remaining three receptacles (figure 4, position 5). With 220V measured voltage, power supply is regular.

#### 8.6 Undervoltage protection testing instruction

 $\Pi 3E2x$  board testing is performed prior to installation, after transporting, in case of system modifications and regular control events, when possible.

#### 8.6.1 Measuring equipment connecting

Connect testing board with  $\Pi 3E2x \ e4$  board according to figure 13.

#### 8.6.2 Setting procedure

After connecting performed in accordance with figure 13, switch off SW1- SW5 switches and DIP switches on  $\Pi 3E9305~e4$  board (SW1-SW3 switch to position "0", SW4 to position 1.8 V/cell and SW5 into position B4).

Set input voltage to 50V value for 48V systems. LED diodes D1 and D2 should be illuminated and others turned off.

VK (contactor switched on) signaling check:

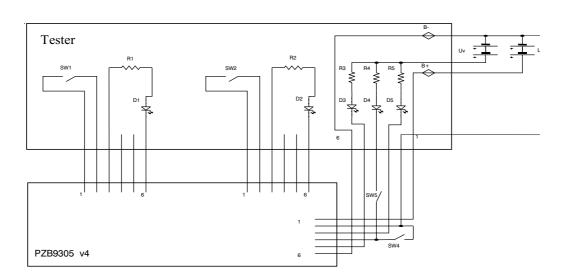


Figure 13: Scheme for connection of  $\Pi 3E2x$  64 testing equipment

Switch on DIP no 1 (to position "1"). If D5 diode illuminates (VK), there is a short circuit. Restore DIP1 to position "0". Repeat same procedure for DIP2.

Switch on pair of switches DIP1 and DIP2. LED diode D5 should illuminate (YK).

In the previous three items, SW1-SW2 switches on testing board were switched off. It remains to check whether VK illuminates for following combinations: SW1 and DIP2, SW2 and DIP1, others switched off.

Additional check of protection activation lower threshold:

Bring signal UK=0 into position "ON" (1.65 V/cell) switching SW4.

Make sure that under voltage protection activation threshold amounts to 1.65 V/cell and deactivation threshold to 1.9 V/cell.

Switch SW4 into position "OFF".

# 8.7 Necessary testing equipment

#### System C2A B4

- universal digital measuring instrument (voltmeter measuring direct voltage up to 100V, 1% precision for 5V value);
- ammeter, AC 50A or current probe;
- thermometer  $(-20^{\circ}C \text{ to} + 100^{\circ}C);$
- thermal load, continuous 0 300A/48V.

#### МДП С36 в4

- universal digital measuring instrument (voltmeter measuring direct voltage up to 100V, with 1% precision for 5V);
- nominal output voltage 48V rectifier M1400T48B~64 with 1% stability or battery with identical characteristics;
- branch feeder set.

#### МРП8А10 в4 network field and Д200А в4 distribution

- universal digital measuring instrument;
- screwdriver.

#### $\Pi 3E_{2x}$ B4 undervoltage protection board

- testing board, according to scheme in figure 13;
- direct source of variable output voltage 30-80V, 100mA;
- direct source for 5V supply, 100mA;
- universal instrument or voltmeter;
- screwdriver for trimmer setting.

# 9 MAINTENANCE INSTRUCTION

C2A 64 system and related assemblies do not require special maintenance procedures. Once installed, system and its assemblies function automatically. This section introduces regular maintenance procedures and reactions in case of failure. All activities in relation to maintenance are performed by personnel trained to operate with supply equipment.

# 9.1 Maintenance and procedures in case of system failure

With  $C2A \ 64$  system operation reliability, only maintenance procedures required are periodical surveillance and elimination of system irregularities reported by the alarms.

System failure results in consumer power dump. Individual assembly failure or fuse blow are not considered system failure.

In case of system failure location failure cause. It may be:

- out of system (network supply dump, battery irregularity, high ambient temperature, power installations disconnection etc.); had an external factor caused the failure, wait until it's being recovered, make sure no damage was brought to the system, and than perform start up according to system installation procedure;
- within system an assembly failure.

System failure is most frequently caused by undervoltage protection failure. Following activities are required:

- make sure the undervoltage protection switch on  $\Pi 3B2x$  board is in position "on";
- check distribution contactor regularity (visually) and coil regularity (ohm check, by disconnection of coil supply);
- check  $\Pi 3E2x$  board regularity:

If irregular, disconnect all distribution fuses (during  $\Pi 3B2x$  replacement), block the contactor in working position, start the system, connect battery and distribution fuses, respectively. System now operates without undervoltage protection and requires continuous personnel surveillance, until failure elimination.

- check regularity of power system installation, distribution, shunts, fuses and rails and replace it when necessary, taking special precautionary measures (switching off the network, rectifiers, disconnecting batteries).
- check contacts on power system installations, distribution, shunts, rails and fuses and fix it if necessary, taking special precautionary measures (switching off the network, rectifiers, disconnecting batteries).

Failure of single assemblies,  $M\square\Pi$ , network field, rectifiers, control logic and similar results in system performances' degrading, without system operation failure.

In case of an assembly failure, repair the assembly or replace the module. Meanwhile, system requires continuous personnel surveillance.

# 9.2 Maintenance and reactions in case of M $\square$ C36 b4 failure

Measuring and diagnostics panel  $M\Pi C36~64$  requires no regular maintenance. After installation,  $M\Pi C36~64$  automatically functions in all regular conditions.  $M\Pi \Pi$  maintenance implies regular operation maintenance and procedures in irregularity conditions.

All procedures are performed by trained personnel.

#### 9.2.1 Maintenance in regular МДП operation

Before testing the  $M \ensuremath{\mathcal{A}} \ensuremath{\Pi}$  operation regularity, make sure that:

- batteries are fully charged;
- proper values of battery and distribution fuses are set;
- appropriate network voltage is conducted;
- all external parameters values are within allowed range.

Also:

- a) Make sure that  $M \ensuremath{\mathcal{A}} \Pi$  displays are functioning correctly and  $M \ensuremath{\mathcal{A}} \Pi$  receives commands from keyboard.
- b) Check whether MДΠ measuring results are correct. System parameters should be measured using universal measuring instrument of 1% precision. Values are compared with values shown on MДΠ displays. Measuring results' check considers: (1) battery voltage, (2) battery current, (3) distribution voltage, (4) distribution current, (5) battery ambient temperature.

If there are certain measured values of system parameters that do not correspond to displayed values with 1% precision, try to eliminate the error checking the apporpirate contacts on measuring shunts. If  $M \square \Pi$  operates irregularly, switch to maintenance mode for  $M \square \Pi$  irregular operation conditions.

c) On false alarm occurred within system, switch off the sound alarm setting the switch to upper position and check connections between  $M \not\square M$  board and fuses, shunts, back panel etc. Also check all connector contacts. If connections from  $M \not\square M$  toward other system elements are correct, device should be sent for servicing.

- d) If there is no sound alarm after switching  $M \square \Pi$  on (position "1") system is functions regularly. On the occurrence of alarm indicator, (sound alarm not deactivated), without a sound alarm reported, check connection between buzzer and  $M \square M (2 \text{ pin connector})$ .
- e) Reported alarm indicates system irregularity and provides information of particular irregular conditions.

On failure indication, check *LCD* display status. Following alarms and failures may occur:

1. BATTERY UNDERVOLTAGE (IIE)

On battery voltage drop below undervoltage alarm threshold, an alarm is reported warning about possible activation of  $\Pi 3B$  protection on 1.8V/per cell (54V) voltage and automatic consumer disconnection. It is necessary to establish network voltage (if possible), bring consumption to minimum or substitute supply source (e.g. switching the aggregate unit on).

2. IRREGULAR DISTRIBUTION VOLTAGE (НД)

Distribution voltage out of range. Possible causes:

- a) Battery voltage (charging mode in accordance with manufacturer notes, current battery storage temperature) is out of range defined by corresponding regulations. Provide appropriate air conditioning.
- b) Frequent network failures or persistent limiting operating conditions of system rectifiers. Temporary jump of distribution voltage might occur.

# 3. IRREGULAR RECTIFIER (НИ)

- a) Make sure all rectifiers are switched on.
- b) Check rectifier connections by pulling out the module and restoring it back to cabinet rack.
- c) If there is a rectifier technically irregular for a considerable period of time, replace corresponding module.
- d) Certain rectifier may be switched off for temperature protection. If such protection type is repeated for one module, replace the module.
- e) Rectifier failure. Replace the module.
- 4. BATTERY FUSE (BO)
  - (a) On fuse blow detected, voltage on fuse endings exceeds 1V. Maximum voltage value in operating conditions is 200mV. Replace the fuse.

- 5. DISTRIBUTION FUSE (ДО)
  - (a) Do not perform ohm check for distribution fuses, voltage check solely. Regular fuse voltage value is under 200mV, irregular fuse voltage exceeds 20V. Replace the fuse.
- 6. IRREGULAR NETWORK VOLTAGE (AM)
  - a) There is a possibility of network fuse blow within distribution cabinet, with one of three modules out of function or, on two phase failure, one of three modules in function. Besides, one of a network field fuses (rectifier fuse) may blow as well. Replace the fuse. Consult C3000 system distribution manual.
  - b) Network voltage level is out of range defined for safe system operation (187-253V), for any phase. (AM) signal is reported.
- 7. TEMPERATURE OUT OF RANGE (TE)
  - a) Displayed value is 20.0°C or 19.9°C, indication exists of something being wrong with the probe or its being disconnected. Switch to maintenance irregular operation mode.
  - b) For temperature being out of range,  $0.0^{\circ}\mathrm{C}$  to 35.0°C, provide battery air conditioning.
- 8. Temporary failure of several modules or a group of modules.
  - (a) See section 6.

#### 9.2.2 MДП irregular operation procedure

All procedures for failure elimination should correspond to those described in user documentation for a specified device. Numbers in brackets present numbers of relating procedures listed in text entitled "Reactions in case of failure".

- 1.  $M\square\Pi$  is not operating, no display or LED diode is illuminated.
  - (a) (3), (2), (6)
- 2. LED or LCD display is not functioning or keyboard is not receiving no commands.

(a) (3), (2), (6)

- 3. *LED* or *LCD* display incorrect.
  - (a) (3), (2), (6)

- 4. One or more modules operate(s) irregularly.
  - a) (9)
  - 6) LED display of certain modules 0.1V 0.2V outputs (8), (2), (5).
  - B) Consult documentation for corresponding module and follow its instructions.
- 5. Signaling is incorrect or alarm is reported.
  - (a) Following failures might have occurred: 6, 7, 8, 9, 10, 11, 12 (one or several of them). Also, there is no expected signaling. See other items.
- 6. BATTERY UNDERVOLTAGE (IIE)
  - a) Check (measuring instrument) confirms the irregular signal (2).
  - б) State unmodified (6).
- 7. IRREGULAR DISTRIBUTION VOLTAGE (НД)
  - (a) Act as for the case of battery undervoltage.
- 8. IRREGULAR RECTIFIER (НИ)
  - a) (8).
  - 6) If generated together with AM see signaling 12, otherwise (2).
  - B) Consult rectifier documentation and act accordingly; if alarm is still reported, (6).
- 9. IRREGULAR SERIAL CONVERTER (HCK)
  - (a) Act as for the case of irregular rectifier.
- 10. BATTERY FUSE (EO)
  - a) If system fuse is regular, check wire form contacts on the fuses and J1  $M \not\square M$  connector.
  - б) State unmodified (6).
- 11. DISTRIBUTION FUSE (ДО)
  - (a) Act as for the battery fuses.
- 12. IRREGULAR NETWORK VOLTAGE (AM)
  - a) With irregular rectifier signal coming along with this one, (5).
  - b) State with no changes or no generation of signal (2), (6).

- c) Replace irregular network fuse, if found any, otherwise make sure that network voltage is in the allowed range 187-253V for each phase, or eventually, consult rectifier user documentation.
- 13. TEMPERATURE OUT OF RANGE (TE)
  - (a) Displayed temperature value differs from real temperature value
    - Displayed value is 20.0°C, indication of something being wrong with the probe or its being disconnected (4).
    - No changes to the state, (6)
    - Displayed value is 19.9°C, probe is short-circuited. Try to eliminate the failure at the probe itself or remove the probe when switching the system to automatic maintenance with 20.0°C temperature.
    - No changes to the state (6).
    - Displayed value deviation from the real one more than 5.0°C (6).
- 14. Wrong output or irregular voltage measuring
  - a) Check distribution contacts on B+ and B- rails.
  - b) All contacts regular (2), (6).
- 15. Wrong output or current measuring
  - a) Check contacts on measuring shunts
  - b) All contacts regular (2), (6).
- 16. Wrong output or temperature measuring
  - a) Check contacts on measuring probe serial terminals
  - b) All contacts regular (2),(6).
- 17. Certain failure or regular state is not registered.
  - (a) (2), (6)
- 18. Remote alarm is not registered
  - a) With all conditions provided for remote alarm, perform ohm check on distribution remote alarm terminals.
  - b) Relay is not short-circuited (2), (6).
- 19. Other failures
  - (a) (1)...(9).

#### 9.2.3 Procedures related to failure

- 1 make sure that  $M\square\Pi$  back switch is in position ON (variants C2 and C3).
- $2\,$  reset  $M\!{\not \perp}\Pi$  using back device switch.
- 3 check connectors J1 and J2 on  $M / \!\!\!/ M M$  and J1 and J2 on both Y M K devices.
- 4 check connection of serial terminals for temperature probe.
- 5 replace irregular module(s).
- 6  $M \square \Pi$  is sent for manufacturer servicing in case previous checks were realized, and it is still not operating.
- 7 check connectors on  $\varPi 3B$  board.
- 8 check back panel bus connectors.
- $9\,$  check module connection.

System reset switches are provided only in C2 and C3 systems. Setting these switches on and off, all controllers and processors in the entire switching supply system are reset. These switches should be used in following situations: *LED* display has blocked or "freezed", *LCD* display has blocked and  $M \square M$  has no indication (no lamp or display is active) or, rectifiers are technically irregular and divided into two current groups.

# 9.3 Maintenance and procedures in relation to Д200А в4 distribution failure

Distribution maintenance includes periodical visual check of distribution, signaling wire form, shunts, contactors, fuse bearings and junctions in power circuits.

Possible failure types are:

# a) Battery supply dump

Red *LED* indicator for fuse blow are illuminated on measuring and diagnostics panel. BO signal appears in alarm status menu. The battery fuse should be replaced with a regular one. Measuring the voltage, detect the burned fuse. After replacing the fuse with a regular one, alarm indicators turn off.

b) **Consumer voltage dump** Red *LED* indicators for fuse blow are illuminated on measuring and diagnostics panel. ДО signal appears in the alarm status menu. Check distribution fuse menu or perform voltage measuring on distribution fuses to detect the irregular fuse. After replacing the fuse with a regular one, ДО indicator turns off.

# c) Distribution part irregularity

In case of irregular signaling wire form, shunts, contactors or fuse bearing irregularity, replace it with a regular part. Existing part is demounted and replaced with a regular one. Do not perform replacement procedure in the energized state (if not necessary). Also apply special precautionary measures to avoid unwanted connections and exchange failure.

# 9.4 Maintenance and procedure in relation to MPП8A10 в4 network field failure

Network field maintenance includes periodical visual check of wire form, fuse bearings, switch and junctions in power circuits.

Two failure types might occur in network field: complete consumer (rectifier) power dump and partial consumer power dump.

# a) Network power dump detection

On network power dump, control lamps are turned off (figure 4, position 3). AM indicators on measuring and diagnostics panel are illuminated. OV is phase voltage. Make sure the main switch (figure 4, position 2) is in position "1". Than proceed with item b).

#### b) Network power dump

Measure voltage values using universal measuring instrument, via measuring receptacles (figure 4, position 4 and 5). If no network voltage is detected, check fuse regularity and switch position in main distribution cabinet supplying network field. Having all of these devices regular, follow the item c).

# c) Irregular main switch

Main switch is irregular. Remove it and instal a regular one. De-energized state only. Switch the network field off and open it. Unscrew the switch handle screw and remove it. Remove the switch mask.

Unscrew the switch screws (4 pieces) and detach the switch from the front board. Break off the wires unscrewing the switch screws. Mount a new fuse in a reverse order.

# 9.5 Maintenance and procedures in relation to $\Pi 3E2x B4$ failure

Undervoltage battery protection  $\Pi 3B2x$  requires no regular maintenance. After installation,  $\Pi 3B2x$  functions automatically in all regular conditions.  $\Pi 3B2x$  maintenance is reduced to maintaining procedures in case of failure or threshold synchronization procedures required after certain system changes or eventual  $\Pi 3B$  setting difficulties.

#### 9.5.1 **П**3**Б**2**x B**4 check and detect procedures

In failure conditions,  $\Pi 3B2x$  takes following steps:

#### a) Failure detection

Two failure types are possible:

-  $\Pi 3B2x$  maintains contactors switched on, battery voltage below protection threshold;

- contactors switched off, voltage within allowed range.

First case is less probable since the lowest voltage value having contactors still switched on is the one within protection threshold level, so the contactor shall "loose" although  $\Pi 3E2x$  has failed.

In all other cases, failure is detected only after considerable battery discharge.

Second type of failure is more obvious since consumers are left with no supply, although battery voltage is within allowed range, which is easily detected measuring the battery voltage.

#### b) Irregular II3B2x board detection

In a system with several  $\Pi 3E2x$  boards, each board is connected to two contactors. Consequently, the irregular board is easily detected according to irregular contactor activity the board is connected to.

# c) Indication check

 $\Pi 3B2x$  state indication is performed over LCD on  $M \square \Pi$ .

If receiving the incorrect indication, check  $\Pi 3B$  board microswitch state. Repositioning the switch during contactors being switched on has no effect since contactors are switched over (make sure not to leave them in a wrong position, causing irregular indication). Set microswitches to regular position, according to instruction manual.

Having set the microswitches correctly, check connections from contactor to  $\Pi 3B$  board; there might be an interruption or short circuit on wires and contacts.

# d) Procedures on undervoltage protection inactivity

- Check protection threshold value. If not properly set, in accordance with instruction manual, do so.

- Measure gate voltage for corresponding FET. Voltage value should not exceed 0.2V. For all values exceeding this limit, board shall be irregular, requiring replacement. If remaining under 0.2V, FET might be irregular or contactor connection touching B-.

- Separate connector using active contactor. If contactor is still active, replace connector and check connections in distribution signaling wire form. Should contactor switch off, replace the board and let serviced.

#### e) Procedures on contactor inactivity

- Check protection threshold. If it's considerably high, reset it. If necessary, proceed with following option.

- Ohm check the contactor receptacle and its diode regularity. Disconnect contactor off  $\Pi 3B2x$  board and perform checks.

- Check connector contacts on  $\varPi 3B2x$  board.

- Make sure there is no interruption on  $\Pi 3 B$  board - contactor connection.

- On fuse activity detected on  $\Pi 3B$  board, disconnect connector from relating contactor on  $\Pi 3B$  board, replace the fuse and check FET and gate voltage on FET (over 1.5V). Had no failure been detected in previous procedures, replace the board.

**Note:** During all measuring and/or intervention processes on  $\Pi 3B$  board IT IS NECES-SARY TO BLOCK SWITCHING CONTACTS IN THE OPERATING POSITION, to avoid unexpected power dump and consumer operation suspension (exchange failure).

#### 9.5.2 **Π3E2x** board replacement

Π3Б board replacement is a very simple procedure, realized in several steps:

- a) Block contactors controlled by the board.
- b) Remove connectors from the board.
- c) Loosen the screws on the board and remove the board.
- d) Install a new board following the procedure described in section 6.

#### 9.6 Necessary equipment

#### Equipment required for МДП C36 в4 maintenance

- universal measuring instrument for voltage check up to 100V and ohm contact values;
- screwdrivers.

#### Equipment required for I1400T48B B4 maintenance

- 2 universal digital instruments or voltmeter for alternative (network) voltage measuring and a voltmeter for direct voltage measuring (up to 200V), with 1% precision on 50V (0.5V)
- current probe 60Amp

- variable load unit 48V, 0-30A
- branch feeder set
- autotransformer 14A, 230V
- $\bullet~{\rm screwdriver}$
- oscilloscope
- spare board set: PRL, PWN, ILG
- spare lamp
- spare network and transistor fuses

#### Equipment required for $\Pi 3E2x B4$ board maintenance

- spare fuse kit
- thin, flat screwdriver for potentiometer setting
- spare  $\Pi 3E2x$  board.

# 10 ABBREVIATIONS

#### CYRILLIC ABBREVIATIONS

- АЛМД remote alarm AM network alarm
- ANInetwork and inBObattery fuse
- ДО distribution fuse
- ИК contactor switched off
- ИСЗВ sound alarm switched off
- MДП measuring and diagnostics panel
- MДM measuring and diagnostics module
- MMH network voltage measuring
- MPΠ network field
- HД distribution voltage
- НИ irregular rectifier
- HCK (HC) irregular serial converter
- ΠБ battery undervoltage
- ПЗБ undervoltage battery protection
- ΠHC undervoltage signal
- PP duty
- TE (TEM) temperature out of range
- 3JIITT Yugoslav post, telephone and telegraph community
- VMKsmall universal converter
- YK contactor switched on

# LATIN ABBREVIATIONS

- AC alternating current
- DC direct current
- LCD liquid crystal display
- LED light-emitting diode
- FAS frame alignment signal
- FET field effect transistor
- $RS485 \quad recommended \ standard \ 485$

# 11 SUPPLEMENT LIST

# 11.1 MATERIAL SPECIFICATION

- 1. Material specification for  $M \slash M 0402$
- 2. Material specification for YMK0102
- 3. Material specification for  $\Pi 3E2x~e4$
- 4. Material specification for network field  $MP\Pi 8A10~e4$
- 5. Material specification for distribution  $\mathcal{A}200A$  64

# 11.2 CONNECTOR PIN POSITIONING

- 1.  $M\square\Pi$  C36 64 connector pin positioning
- 2.  $\Pi 3E2x \ e4$  board connector pin positioning
- 3. YMK0102 board connector pin positioning, I and II
- 4. Back panel connector pin positioning
- 5. Distribution connector pin positioning

# 11.3 ELECTRICAL SCHEMES

- 1. MPII8A10 64 network field wiring scheme
- 2.  $\square 200A \ e4$  signaling distribution scheme
- 3. Electrical scheme of network and distribution lines in C2A cabinet
- 4. Back panel electrical scheme
- 5. Back panel installation scheme